SCRE3NLINE the screen makes the difference

Operating Instructions for Control CS 310 FU

GB





1. **Contents**

| 1. | Contents | 2 |
|-----|----------------------------------|----|
| 2. | Information in this document | 2 |
| 3. | General safety instructions | 3 |
| 4. | Product overview | 4 |
| 5. | Initial operation | 8 |
| 6. | Initialisation | 17 |
| 7. | Setting the end positions | 18 |
| 8. | Programming | 20 |
| 9. | Frequency converter | 22 |
| 10. | Navigator (LCD monitor only) | 26 |
| 11. | Overview of functions | 28 |
| 12. | Error messages and rectification | 45 |
| 13. | Technical data | 49 |
| 14. | Maintenance | 51 |
| 15. | EC Declaration of Conformity | 52 |
| 16. | Appendix | 54 |

Information in this document 2.

Original operating instructions

- Copyright.
- No part of these instructions may be reproduced without our prior approval.
- Subject to alterations in the interest of technical progress.
- All dimensions given in mm.
- The diagrams in this manual are not to scale.

Key to symbols

\Lambda DANGER!

Indicates a hazard with a high level of risk which, if not avoided, will result in death or serious injury.

WARNING!

Indicates a hazard with a medium level of risk which, if not avoided, could result in death or serious injury.



A CAUTION!

Indicates a hazard with a low level of risk which, if not avoided, could result in minor or moderate injury.

ATTENTION!

Indicates an imminent danger of damage or destruction.

CHECK

Indicates a check to be performed.

i REFERENCE

Reference to separate documents which must be complied with.

- Action request
- List, itemisation
- → Reference to other sections of this document



3. General safety instructions

🛕 DANGER!

Failure to comply with the documentation could result in life-threatening danger!

Be sure to follow all the safety instructions in this document.

Warranty

The function and safety of the equipment is only guaranteed if the warning and safety instructions included in these operating instructions are adhered to.

MFZ Antriebe GmbH + Co. KG is not liable for personal injury or damage to property if these occur as a result of the warnings and safety advice being disregarded.

MFZ does not accept any liability or warranty for damage due to the use of non-approved spare parts and accessories.

Use for the intended purpose

The CS 310 FU control is intended exclusively for the purpose of controlling door systems operated using mechanical limit switches or an electronic end position system (AWG absolute value encoder).

Target group

Only qualified and trained electricians may connect, programme and service the control.

Qualified and trained electricians must meet the following requirements:

- knowledge of the general and specific safety and accident prevention regulations.
- knowledge of the relevant electrical regulations,
- training in the use and care of appropriate safety equipment.
- capable of recognising the dangers associated with electricity.

Instructions regarding installation and connection

- The control is designed with X type terminals.
- The system must be disconnected from the electricity supply before carrying out any electrical work. It must be ensured that the electricity supply remains disconnected for the duration of the work.
- Local protective regulations must be complied with.
- Consult the manufacturer before carrying out modifications or replacing the mains connection cable.

Information concerning operation

- Unauthorised persons (particularly children) should not be allowed to play with permanently installed adjusting or control devices.
- Keep remote controls beyond the reach of children.

Regulations and bases for testing

For connecting, programming and servicing, the following regulations must be observed (the list is not exhaustive).

Construction product standards

- EN 13241-1 (Products without fire resistance or smoke control characteristics)
- EN 12445 (Safety in use of power operated doors -Test methods)
- EN 12453 (Safety in use of power operated doors -Requirements)
- EN 12978 (Safety devices for power operated doors and gates - Requirements and test methods)

EMC

- EN 55014-1 (Radio disturbance, household appliances)
- EN 61000-3-2 (Disturbances in supply systems harmonic currents)
- EN 61000-3-3 (Disturbances in supply systems voltage fluctuations)
- DIN EN 61000-6-2 (Electromagnetic compatibility (EMC)
 Part 6-2: Generic standards Immunity for industrial environments)
- DIN EN 61000-6-3 (Electromagnetic compatibility (EMC)
 Part 6-3: Generic standards Emission standard for residential, commercial and light-industrial environments)

Machinery Directive

- EN 60204-1 (Safety of machinery, electrical equipment of machines; Part 1: General requirements)
- EN ISO 12100 (Safety of machinery general principles for design - risk assessment and risk reduction)



General safety instructions

Low voltage

- DIN EN 60335-1 (Household and similar electrical appliances - Safety - Part 1: General requirements)
- DIN EN 60335-2-103 (Household and similar electrical appliances - Safety - Part 2-103: Particular requirements for drives for gates, doors and windows)

Committee for Workplaces (Ausschuss für Arbeitsstätten - ASTA)

 ASR A1.7 (Technical Regulations for workplaces - Doors and gates)

4. Product overview

4.1 Versions

The following package options are available for the CS 310 FU control:

- CS 310 FU control with LCD monitor
- CS 310 FU control with LCD monitor in housing

All the above versions can be fitted with a plug-in weekly timer, a plug-in radio receiver and a plug-in transmission system (for a closing edge safety device and/or a safety element).

The following options are available for the housing:

- Housing unit with 3-button input unit CS
- Housing with ON/OFF key switch
- Housing with main switch
- Housing with Emergency Stop switch

These operating instructions describe the different connection options and the programming of variants:

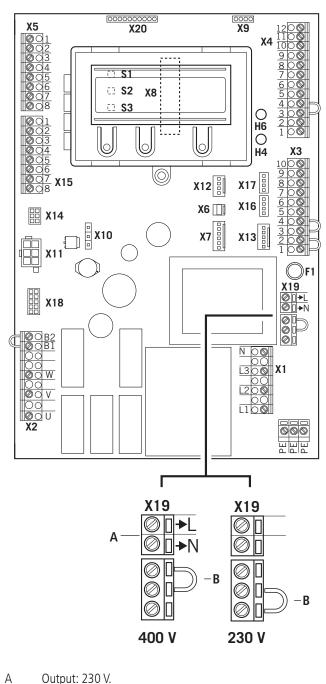
 CS 310 FU control with a connected load of up to and including 4.0 kW, with LCD monitor connected and software version 1.50 or later



4.2 Motherboard CS 310 FU (with plugged-in LCD monitor)

Key:

- X1: Terminal block for mains connection
- X2: Terminal block for motor
- X3: Terminal block for command devices
- X4: Terminal block for safety elements
- X5: Terminal block for relay
- X6: Sockets for internal ON-OFF switch
- X7: Sockets for internal 3-button input unit
- X8: Sockets for LCD monitor (under the LCD monitor)
- X9: Sockets for radio receiver
- X10: Sockets for weekly timer
- X11: Sockets for digital end position system
- X12: Sockets for external radio receiver
- X13: Sockets for CS three-button input unit
- X14: Interface RS 485
 - Connection for CSI button input
 - Connection for RS 485 display
- X15: Terminal block for mechanical end position system
- X16: Sockets for BUS system (MS BUS)
- X17: Sockets for BUS system (MS BUS)
- X18: Frequency converter interface
- X19: Power supply for external devices 230V / 50 Hz protected by F1 (1 A delay) fuse
- X20: Sockets for transmission system
- H4: Standby (green) Lights up when power supply available.
- H6: Status message (red) Lights up when the safety devices are actuated or if an error occurs
- S1: Programming button (+) (under the LCD monitor)
- S2: Programming button (-) (under the LCD monitor)
- S3: Programming button (P) (under the LCD monitor)



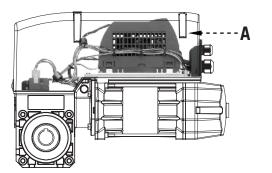
Output: 230 V. Power supply for external devices. No power line entry for the control unit itself.

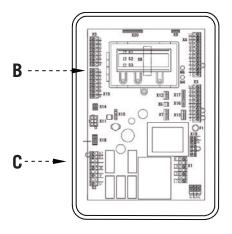
- → "5.3 Power supply for external devices (only for 400 V / 3-phase connection)"
- B The position of the jumper must take into account the power supply voltage and the motor voltage.



Product overview

4.3 Version CS 310 FU-I Frequency converter incorporated in drive, CS 310 control in separate housing

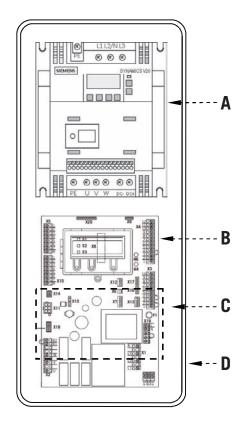




- A Frequency converter
- B CS 310 control
- C Housing

Siemens frequency converter

Type G110 230V/1~/0.75 kW incorporated in drive, for STA series for use with spring-balanced sectional doors, not including brake module or brake resistor 4.4 Version CS 310 FU-E Frequency converter and CS 310 control together in one housing



- A Frequency converter
- B CS 310 control
- C Brake module / brake resistor (under the PCB)
- D Housing

Siemens frequency converter

Type G110 230V/1~/0.75 kW in "Kombi" housing for STA series,

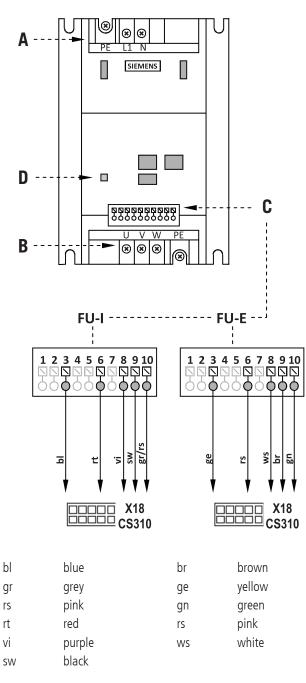
not including brake module or brake resistor

Type V20 230V/1~/0.75 kW in "Kombi" housing Type V20 230V/1~/1.5 kW in "Kombi" housing Type V20 400V/3~/1.5 kW in "Kombi" housing Type V20 400V/3~/3.0 kW in "Kombi" housing Type V20 400V/3~/4.0 kW in "Kombi" housing for MTZ, MDF, SDO series,

including brake module or brake resistor

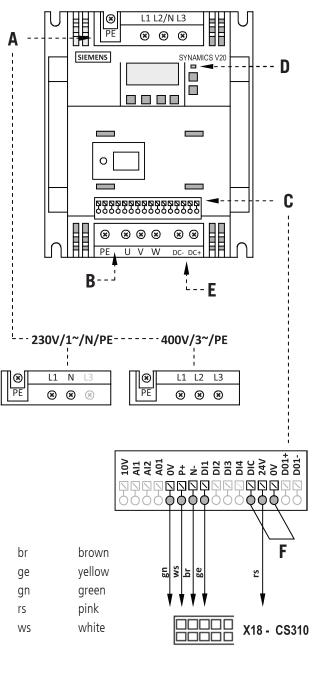


4.5 Connection of Siemens G110 frequency converter



- A Voltage supply, 230V/1~/N/PE (supplied through CS310 / X2)
- B Motor output, 230V/3~/PE
- C Plug-in connection for FU data cable (different colour coding for FU-I and FU-E)
- D LED FU operation

4.6 Connection of Siemens V20 frequency converter



- A Voltage supply, 230V/1~/N/PE or 400V/3 (supplied through CS310 / X2)
- B Motor output, 230V/3~/PE or 400V/3~/PE
- C Plug-in connection for FU-E data cable
- D LED FU operation
- E Brake module connection, DC+/DC-(connection for brake resistor on brake module)
- F Bridge (MUST be used)



5. Initial operation

5.1 General

To guarantee that the equipment functions properly, it must be ensured that:

- The door is installed and operational.
- The MFZ operator motor is installed and ready for operation.
- The command and safety devices are installed and ready for operation.
- The control housing with the CS 310 FU control is installed.

i REFERENCE

The relevant manufacturers' instructions must be adhered to for the installation of the door, the MFZ motor, and the command and safety devices.

5.2 Mains connection

Preconditions

To guarantee that the controls function properly, the following points must be ensured:

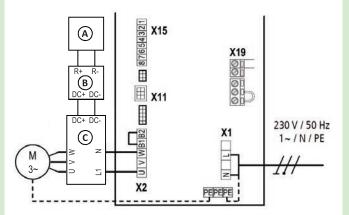
- The mains voltage must correspond to the voltage stated on the type plate.
- The mains voltage must be the same as the input voltage of the frequency converter.
- The output voltage of the frequency converter must be the same as the supply voltage for the operator.
- For a permanent connection, an all-pole main switch must be used.
- For a three-phase connection, only 3-way automatic circuit breakers may be used.

ATTENTION!

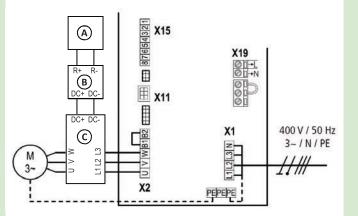
Malfunctions can occur as a result of incorrect installation of the control!

- A frequency converter can also generate purely DC residual currents in the event of a fault. Any residual current current device (RCD) used must therefore be a type B or a type B+ (VDE 0100-530, 531.3.2).
- Before switching on the control for the first time, a check must be carried out after completing the wiring to ensure that all the motor connections on the motor and the control are securely fixed. All control voltage inputs are galvanically isolated from the supply.

Detailed circuit diagram for mains connection and motor connection (230V / 1-phase / 0.75 kW / 1.5 kW)



Detailed circuit diagram for mains connection and motor connection (400 V 3-phase / 1.5 kW / 3.0 kW / 4.0 kW)



- A Brake resistor
- B Brake module
- C Frequency converter



Key:

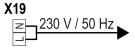
M1: Motor

- X1: Terminal block for mains connection
- X2: Terminal block for motor
- X11: Sockets for digital end position system with safety circuit (SAFETY CIRC.)
- X15: Terminal block for mechanical limit switches (Safety circuit at X2 / B1-B2)
- X19: Power supply connection for external devices

Connection:

- Connect the digital end position system to X11, and/or mechanical limit switches to X15 of the control.
- Sonnect FU (A) voltage supply to X2 of the control.
- Sonnecting the motor to the frequency converter.
- Sonnect FU (C) data cable to X18 of the control.
- Sonnect the control to the mains power supply.
- Cable groups must be secured close to their relevant terminals using a cable tie.
- → "13. Technical data" on page 49

5.3 Power supply for external devices (only for 400 V / 3-phase connection)

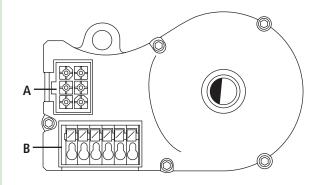


NOTICE:

The X19 connection can only be used with a 400 V / N / $3\sim$ power supply.

Terminal X19 is protected with fuse block F1 (1 A-T).

5.4 Allocation of connections for absolute value encoder (sockets X11)



- A: AWG plugs
- B: AWG plug terminal

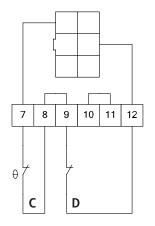
X11 sockets (at connection A)



The numbers on the plug are also the wire numbers:

- 4: Safety circuit input
- 5: RS 485 B
- 6: GND
- 7: RS485 A
- 8: Safety circuit output
- 9: 12V _{DC}

Sockets B (absolute value encoder only)



- C: Thermal element in door/ gate operator
- D: Emergency manual operation (emergency hand crank or
 - emergency hand chain)

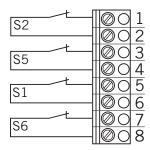
The end position system will be recognised automatically by the control during initial use. If a change is made at a later date, the relevant end position system must be selected via a parameter setting in INPUT mode.



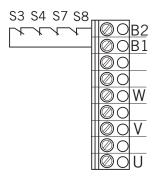
Initial operation

5.5 Connection of mechanical limit switches (terminal blocks X15 and X2)

Terminal block X15



Terminal block X2

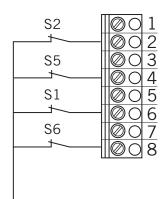


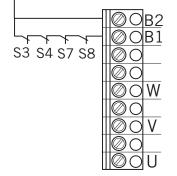
The end position system will be recognised automatically by the control during initial use and following a RESET. If a change is made at a later date, the relevant end position system must be selected via a parameter setting in INPUT mode.

→ "11.2 Input operating mode"

Connection example for solution with 6 leads

Terminal blocks X11 and X2





- S1 Additional limit switch, (braking point) OPEN
- S2 Limit switch, OPEN
- S3 Safety limit switch, OPEN
- S4 Safety limit switch, CLOSED
- S5 Limit switch, CLOSED
- S6 Additional limit switch, (braking point) CLOSED
- S7 Thermal overload protection for motor
- S8 Emergency operation (n.c. contact)

NOTICE:

If two mechanical limit switches are used, it is essential that there are two additional limit switches for setting the braking points.



5.6 Connection of command devices

CAUTION!

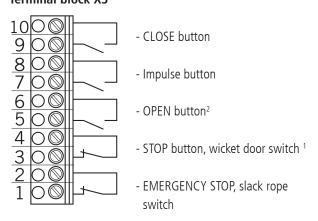
Danger of injury due to uncontrolled movement of the door!

A CLOSE command for deadman mode without the door being in sight may be enabled only via Input 1 / MOD32 (X4 / 9–10). INSTALL command devices for deadman operation in direct

sight of the gate, but outside the danger area for the user. If the command device is not a key switch:

Install it at a height of at least 1.5 m off the ground.
 Install it so as to make it inaccessible to the general public.

Terminal block X3

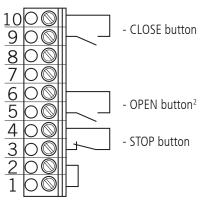


¹Wicket door switch only possible as a contact with positive separation.

5.7 Connection examples for command devices (terminal block X3)

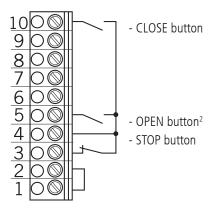
OPEN / STOP / CLOSE buttons

6-lead solution

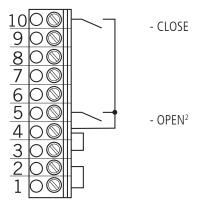


OPEN / STOP / CLOSE buttons

4-lead solution

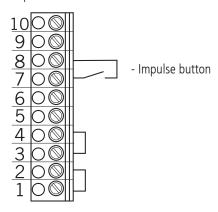


Key switch OPEN / CLOSE



Impulse button

sequence control



² If two-way traffic control is activated: OPEN button inside



Initial operation

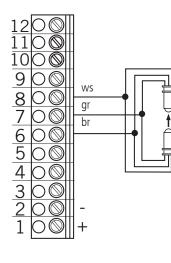
5.8 Connection of closing edge safety device 1

The closing edge safety device will be recognised and programmed automatically during initial use and following a RESET. If a closing edge safety device is not connected, the input will be queried every time the power supply is switched on again, until a closing edge safety device is recognised. If a change is made at a later date, the relevant system must be selected via a parameter setting in INPUT mode.

→ "11.2 Input operating mode"

Terminal block X4

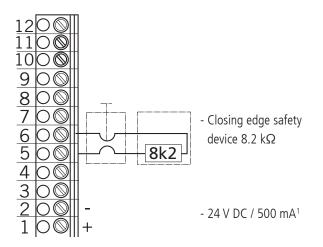
Opto-electronic closing edge safety device "SKS" parameter setting = MOD 1



ws: white gr: green br: brown

Terminal block X4

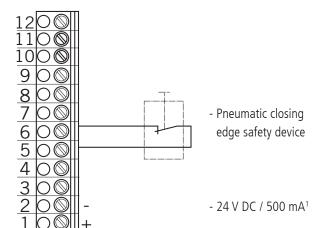
Electrical closing edge safety device (8.2 k Ω) "SKS" parameter setting = MOD 2



Terminal block X4

Pneumatic closing edge safety device (pressure sensor test) "SKS" parameter setting = MOD 3

- Testing is activated automatically



¹ for external switching devices (connection to terminals 1 and 2)



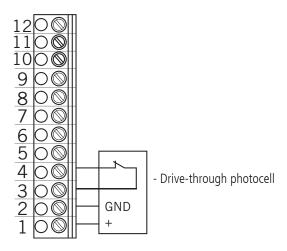
5.9 Photocell connection 1

The photocell system will be recognised and programmed automatically during initial operation and following a RESET. If a photocell system is not connected, the input will be queried every time the power supply is switched on again, until a closing edge safety device is recognised. If a change is made at a later date, the relevant system must be selected via a parameter setting in INPUT mode.

→ "11.2 Input operating mode"

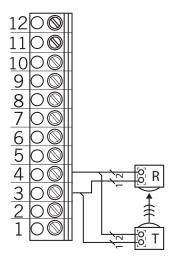
Terminal block X4

Photocell NC Parameter LIGHT BARR. 1 = MOD 2



Terminal block X4

MFZ two-wire photocell Parameter LIGHT BARR. 1 = MOD 1

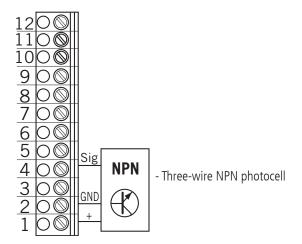


R: Receiver

T: Transmitter

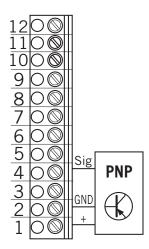
Terminal block X4

Three-wire NPN photocell Parameter LIGHT BARR. 1 = MOD 2



Terminal block X4

Three-wire PNP photocell Parameter LIGHT BARR. 1 = MOD 3



- Three-wire PNP photocell

NOTICE:

All photocells are active in the OPEN or CLOSE direction, depending on the setting.

→ "11.2 Input operating mode"



Initial operation

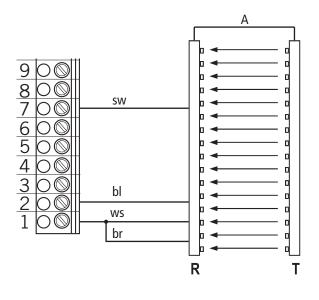
5.10 Light curtain connection

Up to two light curtains can be connected to the CS 310 FU. Light curtain 1 is connected to the input of the closing edge safety device and can be either an OSE or PNP system.

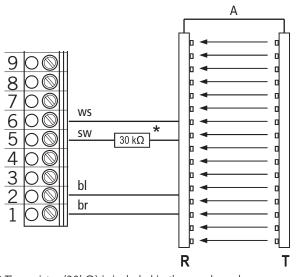
Terminal block X4

Light curtain 1

Version A: OSE (parameter SKS = MOD4) The connecting cable (A) can be plugged in.



Version B: PNP (parameter SKS = MOD5) The connecting cable (A) can be plugged in.

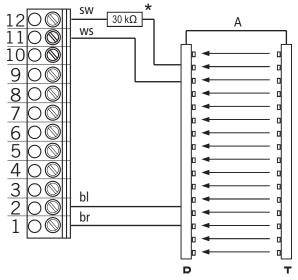


* The resistor ($30k\Omega$) is included in the supply package.

Light curtain 2 (parameter INPUT2 = MOD7)

Light curtain 2 is connected to the programmable INPUT 2 and must be a PNP system.

The connecting cable (A) can be plugged in.



* The resistor (30k Ω) is included in the supply package.

| br: | browr |
|-----|-------|
| bl: | blue |

- sw: black
- ws: white

NOTICE:

The light curtain shown as an example in these instructions is the RAY-LG, manufactured by FRABA/CEDES.

RAY-LG 25xx OSE RAY-LG 15xx PNP

In the case of the PNP system, the resistor $(30k\Omega)$ is included in the supply package and must be wired into the system without fail.

Testing of the FRABA/CEDES RAY-LG 15xx PNP light curtain takes place cyclically at the upper end position and before every hazardous movement. No relay output is necessary in this case.

No testing is required for the RAY-LG 25xx OSE light curtain.

Drawings from other manufacturers are available on enquiry.



5.11 Connection of programmable inputs

The CS 310 FU control has two programmable inputs, for which various functions can be selected. → "11.2 Input operating mode"

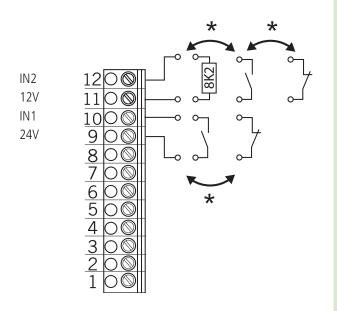
ATTENTION!

Danger of damage to the circuit board due to incorrect connection!

Inputs 1 and 2 have a different reference potential and they must NOT be operated from the same potential!

Terminal block X4

Programmable inputs Input 1: Terminal 9 + 10 Input 2: Terminal 11 + 12



IN1 Input 1 IN2 Input 2 * either/or

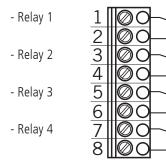
The type of wiring depends on the parameter settings for both inputs in INPUT mode.

5.12 Connection arrangement for relay outputs

Four potential-free relay outputs are available which can be programmed for various types of function.

→ "11.2 Input operating mode"

Terminal block X5



Internal switching contacts of the relays

These four relay outputs are potential-free and have a maximum capacity of 4A at 230V/1~.

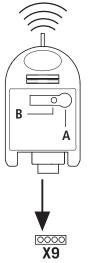
The type of function depends on the parameter setting for the corresponding relay output in INPUT mode.



Initial operation

5.13 CS radio

Terminal block X9



Connection

Insert the plug-in receiver into plug-in socket X9.

Teaching-in the transmitter codes

Press the programming button (A) and hold for more than 1.6 seconds. The programming mode is activated. The LED (B) flashes.

Press the channel button on your transmitter.

Once the remote control has saved the transmitter code, the LED lights up for approximately 4 seconds.

It is possible to teach-in up to 15 transmitter codes. If all memory spaces are full, the LED flashes rapidly.

Selectively deleting a transmitter code

- Press the programming button (A) and hold for more than
 1.6 seconds. The programming mode is activated.
 The LED (B) flashes.
- Keep pressing the programming button. The delete mode is activated. The LED flashes very fast.
- Press the required channel button on your transmitter. When the LED lights up for approximately 4 seconds, the transmitter code in question has been deleted.

The deletion procedure can be cancelled by briefly pressing the programming button.

RESET (DELETE ENTIRE MEMORY)

- Press the programming button (A) and hold for more than
 1.6 seconds. The programming mode is activated.
 The LED (B) flashes.
- Keep pressing the programming button. The delete mode is activated. The LED flashes very fast.
- Press the programming button again for more than 1.6 seconds.

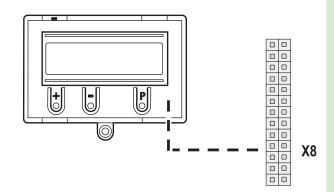
When the LED lights up for approximately 4 seconds, all of the memory spaces have been deleted.

The deletion procedure can be cancelled by briefly pressing the programming button.

5.14 Connection of LCD monitor

With the LCD monitor, you have complete access to all of the menu settings and parameters of the control unit. → "8. Programming"

Plug-in socket X8



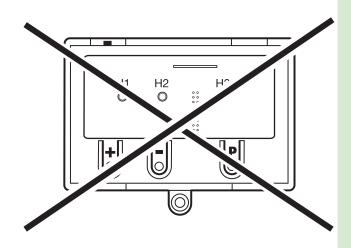
ATTENTION!

Damage can occur through improper installation!

The mains power supply must be switched off before connecting the LCD monitor. Only an MFZ LCD monitor (article number 206023) may be used.

ATTENTION!

Damage can occur through improper installation! The MFZ LED module (article number 590045) cannot be combined with the CS 310 FU. Inserting this module and putting it into service can damage the CS 310 FU circuit board beyond repair.



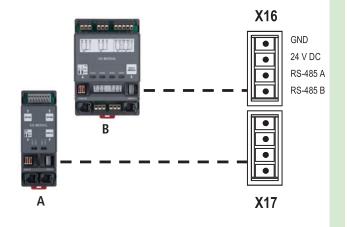


5.15 Connection of MS BUS modules

The MS BUS function modules allow you to expand the existing functions or add further functions.

- ES Module: Evaluation of draw in protection systems
- I/O Module: Input/Output expansion
- GV Module: Two-way traffic control

X16 / X17 sockets



A ES Module

B I/O Module / GV Module

i REFERENCE

For a detailed description of the function and connection of the modules, see the separate documentation for the BUS modules.

NOTICE:

Sockets X16 and X17 can be used only once. Taking the power consumption into account, however, it is possible to connect several BUS modules by using special jumper cables.

6. Initialisation

The following components will be recognised and taught-in automatically during initial operation and following a RESET.

- End position system
- Closing edge safety device
- Photocell system
- Input 2 (wicket door sensor)

During this process (approximately 90 seconds) the green LED flashes and the top line of the display shows the message "PLEASE WAIT ...".

It is not possible to operate the system during this process. The end position system must be installed before initial operation.

Components can be changed or added at a later date using the LCD display or by reinitialising the system. If one of the components has not yet been connected, this will be indicated by "A" in the display. This component will be searched for if any further initialisation procedure is carried out. If this component is recognised, the system automatically switches to the appropriate adjustment mode.

Exception:

Input 2 remains inactive (MOD1) if no 8.2 k Ω resistance was recognised the first time that initialisation was carried out. If an 8.2 k Ω resistance is detected at Input 2 during initial operation, it will be evaluated as a wicket door sensor and set in operation accordingly.

NOTICE:

In addition to "teaching in" the various system components, the initialisation process allows you to change the menu language directly.

The menu language pre-set in the factory (DEUTSCH) is displayed as a flashing text for approximately 60 seconds. The desired language can be selected using the [+] and [-] buttons and saved by pressing the [P] button. After this, all texts or messages displayed are shown in the language that you have selected.



7. Setting the end positions

7.1 Checking the direction of rotation/ direction of travel

TAMPERING OR MODIFICATION OF THE SYSTEM ELECTRIC ON THE UNIT OR ON THE END POSITION, WILL LOSE THE WARRANTY OF THE SCREEN AND ANY RESPONSIBILITY FOR PART OF THE MANUFACTURER. ANY CHANGES WILL BE NOTIFIED AGREED WITH SCREENLINE.

IN ANY CASE THE HEIGHT OF THE FABRIC WILL NOT NEVER BE INCREASED BUT ONLY REDUCED.

Changing to adjustment mode

Reg Press button (P) until ADJUSTMENT appears.

Checking the direction of travel

■ Press the (+) button. The door should open.

 \mathbb{I} Press the (–) button. The door should close.

If correct, continue with setting the end positions. If not, change the direction of travel.

Changing the direction of travel

 Press buttons (+) and (-) at the same time and hold for longer than 5 seconds. The display shows "ROT FIELD LEFT". Any end positions that have been saved will be deleted. Continue with setting the end positions.

7.2 Setting the mechanical limit switches

Changing to adjustment mode

Press button (P) until ADJUSTMENT appears.

Setting the OPEN and CLOSED end positions

i REFERENCE

The procedure for setting the end positions is described in separate documentation for mechanical limit switches.

Series the ADJUSTMENT mode by pressing button (P).

Please note

ADJUSTMENT mode is not exited automatically. To return to normal operating mode, ADJUSTMENT mode must be exited by pressing button (P).

7.3 Setting the electronic end position system using the setting buttons on the circuit board

Changing to adjustment mode

Press button (P) for approx. 5 seconds. The red LED flashes slowly.

Set the OPEN end position

- Press the (+/-) buttons to move the door/gate to the desired OPEN end position.
- Save the end position setting by pressing button (P) and by additionally pressing the (+) button. The red LED flashes rapidly for approx. 1 second.

Set the CLOSED end position

- Press the (+/-) buttons to move the door/gate to the desired CLOSED end position.
- Save the end position setting by pressing button (P) and by additionally pressing the (–) button. The red LED flashes rapidly for approx. 1 second.

Adjustment mode is exited automatically. The red LED goes out.

Please note

- The adjustment mode will end automatically after approximately 7 seconds if no key is pressed.
- When carrying out adjustments for the first time, it is necessary to teach-in both end positions. Otherwise, normal operation will not be possible.
- If an end position is corrected, the ADJUSTMENT menu can be exited by pressing button (P) once the teaching-in of the special end position has been completed.
- After programming the limit switches, the teach-in of the system running time is carried out automatically. The functions of the control are the same as in automatic mode.



7.4 Setting the electronic end position system using the LCD monitor

ATTENTION!

Damage to property or irreparable damage due to incorrect installation!

The power supply must be switched off before connecting the monitor. Only an MFZ monitor may be used.

At plug-in socket X8: At plug-in socket X14:

LCD Monitor Standard (#206023) LCD Monitor RS 485 (#1700004793)

Changing to adjustment mode

Res button (P) until ADJUSTMENT appears.

Set the OPEN end position

INPRESE THE (+/−) buttons to move the door/gate to the desired OPEN end position.

Save the end position setting by pressing button (P) and by additionally pressing the (+) button.
 "STORAGE UP" appears in the display.

Set the CLOSED end position

- INPRESE THE (+/−) buttons to move the door/gate to the desired CLOSED end position.
- Save the end position setting by pressing button (P) and by additionally pressing the (–) button.
 "STORAGE DOWN" appears in the display.

Adjustment mode is exited automatically.

Please note

- The adjustment mode will end automatically after approximately 7 seconds if no key is pressed.
- When carrying out adjustments for the first time, it is necessary to teach-in both end positions. Otherwise, normal operation will not be possible.
- If an end position is corrected, the ADJUSTMENT menu can be exited by pressing button (P) once the teaching-in of the special end position has been completed.
- After programming the limit switches, the teach-in of the system running time is carried out automatically. The display shows TEACH IN RUN. The functions of the control are the same as in automatic mode.

7.5 Setting the intermediate positions of the electronic end position system using the LCD monitor

In AUTOMATIC mode, move the door/gate to the desired position

■ Press the (+/–) button to drive the door to the desired intermediate position (INC.P.OP or INC.P.CL).

Changing to Input mode

- Res button (P) until INPUT appears.
- Press buttons (+) and (-) at the same time for longer than 2 seconds. The first parameter appears in the second line of the display.

Saving the intermediate OPEN (INC.P.OP) or CLOSE (INC.P.CL) position

Press the (+/-) buttons until the parameter INC.P.OP or INC.P.CL appears.

The current value is A.

- Press button (P) to adopt the current door/gate position as an intermediate position.
- Save the intermediate position by pressing button (P) again.

Exiting Input mode

Press buttons (+) and (-) at the same time for approx.
 1 seconds.
 Input mode is exited.

Changing to automatic mode

Res button (P) until AUTOMATIC appears.

Please note

 If an intermediate position requires to be corrected, the teach-in value can be altered in the INPUT menu or set to A again to allow a new teach-in procedure to be carried out.



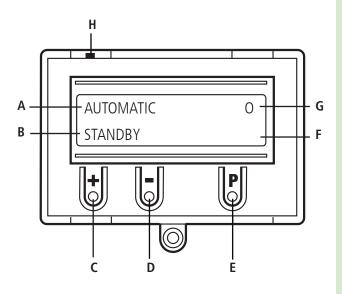
8. Programming

8.1 Overview of the LCD monitor

ATTENTION!

Damage can occur through improper installation!

The mains power supply must be switched off before connecting the display unit. Only a display unit manufactured by MFZ (article number 206023) may be used.



Key:

- A: Mode of operation / Diagnostics info
- B: Parameters / Diagnostics info
- C: Button (+)
- D: Button (–)
- E: Button (P)
- F: Value / Status
- G: Value / Status
- H: Jumper

If jumper H is removed, the (+) button, the (–) button and the (P) button have no function. The display still functions.

After the control has been switched on, it will be in the initialisation phase and "PLEASE WAIT ..." will appear in the display. The control system is not ready for use. After switching on for the first time, the initialisation phase takes approximately 90 seconds.

8.2 LCD monitor, modes of operation

The control has four modes of operation with the LCD monitor:

- 1. AUTOMATIC
- 2. ADJUSTMENT
- 3. INPUT
- 4. DIAGNOSIS

ADJUSTMENT, INPUT and DIAGNOSIS modes are exited automatically 7 seconds after the last button was pressed. The control then goes into AUTOMATIC mode.

Operating mode 1: AUTOMATIC

The door/gate system is operated in the AUTOMATIC operating mode.

Display:

- Displays the action being carried out
- Displays any error messages

If the "PRESS/REL" parameter is set to MOD2–6 in the input menu, the display changes from AUTOMATIC to MANUAL.

Operating mode 2: ADJUSTMENT

ADJUSTMENT mode is used for setting the OPEN/CLOSED end positions.

ATTENTION!

Malfunctions can occur as a result of incorrect operation of the control!

In ADJUSTMENT mode, the door will not stop automatically when it reaches the end position if an electronic end position system (AWG - absolute value encoders) is used. The door can be damaged if driven beyond the end position.

Fine adjustments can be made in the INPUT operating mode.

Display:

- The current end position value is shown



Operating mode 3: INPUT

In the INPUT operating mode, the values of various parameters can be altered.

Display:

- Displays the selected parameter
- Displays the programmed value / current status

Operating mode 4: DIAGNOSIS

In the DIAGNOSIS operating mode, door-specific checks can be queried.

Display:

- Displays the checks
- Displays the status of the checks

8.3 RESET

The RESET function allows you to return the control parameters to the original factory settings.

→ "11.2 Input operating mode"

FACTORY SET. parameter

Selecting the set of parameters that you want to RESET to.

Different types of reset can be carried out, allowing you to reset more or fewer of the settings.

→ "11.2 Input operating mode"

RESET parameter

Partial reset 1:

All of the parameter settings are reset except the settings for the frequency converter (applies only to CS310 FU).

Partial reset 2:

All of the parameter settings are reset except the settings for the end positions and the recognised end position system.

Complete reset:

Everything is returned to the factory default settings.

- → "8.4 RESETTING the control using the LCD monitor"
- → "8.5 RESETTING the control without an LCD monitor"

8.4 RESETTING the control using the LCD monitor

Switch to INPUT mode.

Press the (P) button until "INPUT" appears in the display.

Press buttons (+) and (-) for longer than 2 seconds to activate the Input.

Reset the control

Press the (+/-) buttons until the "RESET" parameter appears in the display.

The value is set to "OFF".

- 🖙 Press the (+) button until MOD4 appears in the display.
- Press button (P) to begin the RESET.

The initialisation phase takes place, and the end position system and all of the safety components that are connected are automatically taught in.

Changing to adjustment mode

→ "7.4 Setting the electronic end position system using the LCD monitor"

Changing to automatic mode

Press the (P) button until "AUTOMATIC" appears in the display.

8.5 RESETTING the control without an LCD monitor

- Solution and the system from the power supply.
- Press the circuit board buttons (P) and (–) at the same time and keep them pressed.
- Switch the power supply back on again.
- Press the circuit board buttons (P) and (–) at the same time and keep them pressed until the red LED (H6) flashes quickly.
- Release the circuit board buttons (P) and (–).

The initialisation phase will then take place (approximately 90 seconds).

While initialisation is being carried out, it is not possible to programme or operate the system.

Once initialisation has been successfully completed, the end positions have then been deleted and all parameters have been reset to their factory default settings.



9. Frequency converter

9.1 General

The frequency converter control allows the door/gate speed to be adjusted separately for the OPEN and CLOSING directions. The frequency of the converter determines the operator speed. This speed-independent controlling of the door/gate system makes the door/gate run smoothly and protects the door/gate mechanism, resulting in benefits such as

- faster response times,
- reduced draughts, and
- minimised heating costs.

The acceleration and deceleration times (SPEED UP / SLOW DOWN) ensure soft starting and stopping at the end positions.

9.2 Adjustable values

The following is a list of parameter settings that are directly related to speed regulation through the frequency converter module.

Various graphs showing the process that takes place at the various settings are given by way of illustration.

→ "9.3 Travel diagrams"

BRAKE P.OP. (Brake point OPEN)

Initiates the deceleration time SLOW DO. OP. The door/gate then continues at minimum speed $\rm f_{\rm SOFTRUN \, OP'}$

This parameter only appears in the menu when the end positions have been programmed, and it then appears as a negative value referred to the upper cut-out point. This can only be set in the menu in conjunction with an absolute value encoder.

If mechanical limit switches are used, the before-end switch OPEN is used as a position marker for speed reduction. *Only applies for OPENING direction of door/gate travel*

BRAKE P.CL. (Brake point CLOSED)

Initiates the deceleration time SLOW DO. CL. The door/gate then continues at minimum speed $f_{\mbox{\tiny SOFTRUN\,CL}}$

This parameter only appears in the menu when the end positions have been programmed, and it then appears as a positive value referred to the lower cut-out point.

This can only be set in the menu in conjunction with an absolute value encoder.

If mechanical limit switches are used, the before-end switch CLOSE is used as a position marker for speed reduction. *Only applies for CLOSING direction of door/gate travel.*

BRAKE P CL 2 (Brake point CL 2)

Allows the door/gate to close at 3 different speeds. The Brake point CL2 initiates the deceleration SLOW DO. MX. The door/ gate movement then continues at normal speed $f_{SPEED CLOSE}$. This parameter only appears in the menu when the end positions have been programmed, and it then appears as a positive value referred to the lower cut-out point.

This can only be set in the menu in conjunction with an absolute value encoder.

This function is not available if mechanical limit switches are used.

Only applies for CLOSING direction of door/gate travel.

SPEED OPEN (normal OPENING speed)

The normal OPENING speed for door/gate movement can be set here. Speed of travel $f_{SPEED OPEN}$. Only applies for OPENING direction of door/gate travel

SPEED CLOSE (normal CLOSING speed)

The normal CLOSING speed for door/gate movement can be set here. Speed of travel $f_{SPEED CLOSE}$. Only applies for CLOSING direction of door/gate travel.

MX SPEED CL. (maximum CLOSING speed)

The maximum speed for door/gate CLOSING movement can be set here. Speed of travel $f_{\mbox{\scriptsize MX SPFED Cl}}$.

This parameter only appears in the menu when Brake point 2 has been programmed, and it then appears as an option. This allows two different fast speeds and one slow speed to be set in the CLOSING direction.

Only applies for CLOSING direction of door/gate travel.

SOFTRUN OP. (minimum OPENING speed)

The minimum speed for door/gate OPENING movement can be set here. Speed of travel $f_{SOFTRUN OP}$, Only applies for OPENING direction of door/gate travel

SOFTRUN CL. (minimum CLOSING speed)

The minimum speed for door/gate CLOSING movement can be set here. Speed of travel $f_{SOFTRUN CL}$. Only applies for CLOSING direction of door/gate travel.

SPEED UP OP. (Speed up OPENING)

The acceleration time that elapses between the starting command and reaching the normal speed $f_{\text{SPEED OPEN}}$. Only applies for OPENING direction of door travel.



SPEED UP CL. (Speed up CLOSING)

The acceleration time that elapses between the starting command and reaching the normal speed $f_{\text{SPEED CLOSE}}$. Only applies for OPENING direction of door/gate travel.

SLOW DO. OP. (Slow down OPENING)

Sets the time that elapses between the Brake point OPEN and reaching the minimum speed $\rm f_{\rm SOFTRUN\,OP}.$ Only applies for OPENING direction of door/gate travel.

SLOW DO. CL. (Slow down CLOSING)

Sets the deceleration time that elapses between Brake point CLOSE and reaching the minimum speed $\rm f_{SOFTRUN\,CL}.$ Only applies for CLOSING direction of door/gate travel.

SPEED UP MX (Speed up MAX CLOSING)

Sets the time that elapses between the starting command and reaching the maximum speed $\rm f_{\rm MX\,SPEED\,CL}.$

This parameter only appears in the menu when Brake point 2 has been programmed, and it then appears as an option. This allows acceleration to a second (optional) fast speed to be set in the CLOSING direction.

Only applies for CLOSING direction of door/gate travel.

SLOW DO. MX (Slow down MAX CLOSING)

Sets the time that elapses between the Brake point CL 2 and reaching the normal speed $\rm f_{\rm SPEED\,CLOSE}.$

This parameter only appears in the menu when Brake point 2 has been programmed, and it then appears as an option. This allows deceleration in the CLOSING direction to be set from a second (optional) fast speed to a normal speed $f_{SPEED CL}$. Only applies for CLOSING direction of door/gate travel.

Reversal of direction by pressing the OPEN or CLOSE button

Depending on the current speed and direction of travel, reversal of the direction by directly pressing the OPEN or CLOSE buttons will result in SLOW DO. OP. / CL. / MX and SPEED UP OP. / CL. / MX being run through.

The total time for reversing the direction is made up of SLOW DO. OP. / CL. / MX (INPUT menu) and SPEED UP OP. / CL. / MX.

Reversal of direction by triggering the closing edge safety device

The parameter SLOW DO. SKS / SPEED UP SKS describe the procedures after triggering the closing edge safety device and the associated direct reversal of direction.

The total time for reversing the direction is made up of SLOW DO. SKS, reversal time (INPUT menu) and SPEED UP SKS

SLOW DO. SKS (Slow down SKS)

Sets the time that elapses between triggering the closing edge safety device and stopping the door/gate system. The countdown for the pre-set reversal time then begins. *Applies for both directions of door/gate travel.*

SPEED UP SKS (Speed up SKS)

Sets the time that elapses between expiry of the reversal time and reaching the normal speed $f_{\text{SPEED OPEN/CLOSE}}$. Applies for both directions of door/gate travel.

Reversal of direction by triggering the photocell (drive-through)

The parameter SLOW DO. LB / SPEED UP LB describe the procedures after triggering the photocell system and the associated direct reversal of direction.

The total time for reversing the direction is made up of SLOW DO. SKS, reversal time (INPUT menu) and SPEED UP LB.

SLOW DO. LB (Slow down LB)

Sets the time that elapses between triggering the closing edge safety device and stopping the door/gate system. The countdown for the pre-set reversal time then begins. *Applies for both directions of door/gate travel.*

SPEED UP LB (Speed up LB)

Sets the time that elapses between expiry of the reversal time and reaching the normal speed $f_{SPEED OPENVCLOSE}$. Applies for both directions of door/gate travel.

Stopping the door/gate system with the stop button or the impulse sequence

SLOW DO. STOP (Slow down STOP)

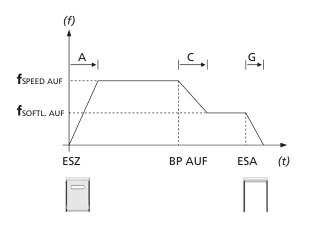
Sets the time that elapses between pressing the stop button or the impulse sequence and stopping the door/gate system. *Applies for both directions of door/gate travel.*



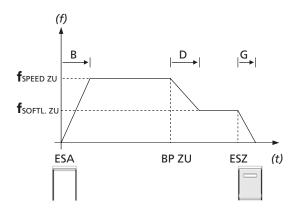
Frequency converter

9.3 Travel diagrams

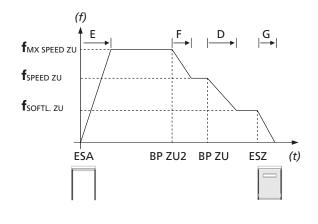
Door/gate opening run with two speeds



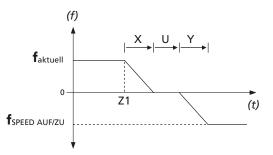
Door/gate closing run with two speeds



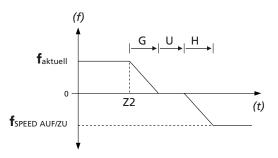
Door/gate closing run with three speeds



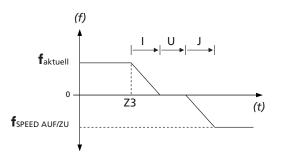
Reversal of direction with OPEN / CLOSE button



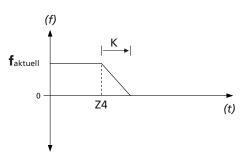
Reversal of direction with closing edge safety device



Reversal of direction with photocell



Operating stop with stop button or impulse sequence





| Key (f) (t) | Frequency Time |
|--|---|
| ESA ESZ BP AUF BP ZU BP ZU 2 | Upper limit switch, OPEN Lower limit switch, CLOSE Brake point OPEN Brake point CLOSED Brake point CLOSED 2 |
| $ \begin{array}{l} f_{sPEED \; AUF} \\ f_{sOFTL \; AUF} \\ f_{sPEED \; ZU} \\ f_{MX \; SPEED \; ZU} \\ f_{sOFTL \; ZU} \\ f_{aktuell} \\ f_{sPEED \; AUF/ZU} \end{array} $ | Frequency SPEED OPEN Frequency SOFTRUN OPEN Frequency SPEED CLOSE Frequency MX SPEED CL Frequency SOFTRUN CL. Current operating frequency Frequency SPEED OPEN or SPEED CLOSE |
| A B C D. E F G H I J K | SPEED UP OP. SPEED UP CL. SLOW DO. OP. SLOW DO. CL. SPD. UP MX SLO. DO. MX SLOW DO. SKS SPEED UP SKS SLOW DO. LB SPEED UP LB SLOW DO. STOP |
| U | Reversal time The reversal time can be set in the INPUT menu item |
| X Y | SLOW DO. OP./CL. or SLOW DO. MX SPEED UP OP./CL. or SPD. UP MX The current operating frequency determines whether slow down/speed up OP./CL. or MX applies. |
| Z1 Z2 Z3 | Button pressed SKS closing edge safety device triggered Photocell triggered |

- Z3 Photocell triggered
- Z4 Stop triggered

9.4 Rated values for motor

In INPUT operating mode, certain motor rating data can be set. It is essential that these settings agree with the information given on the motor type plate. Although these are factory pre-set when supplied in combination with a door/ gate operator, it must be checked before using them for the first time whether the settings comply with the information given on the type plate. It is essential that the following data is checked and set:

| MOTOR V | Rated voltage of motor |
|-----------|--------------------------|
| MOTOR I | Rated current of motor |
| Motor P | Rated power of motor |
| MOTOR PHI | Power factor of motor |
| MOTOR I | Rated frequency of motor |
| MOTOR RPM | Rated speed of motor |

In addition, it is possible to set the limits for the minimum and maximum operating frequency of the motor. The parameters required for this purpose can also be found in INPUT operating mode:

MOT.HZ MINLowest programmable operating frequencyMOT.HZ MAXHighest programmable operating frequency

The maximum programmable operating frequency of a motor is determined by the manufacturer and must be individually checked and set.

ATTENTION!

Damage can occur through improper installation! Incorrectly entering the parameter settings described can result in considerable damage occurring to the control unit and motor.



10. Navigator (LCD monitor only)

| | $ \begin{array}{c} \bigoplus \\ \bigoplus \\ \bigoplus \\ \text{MAIN UP} \\ \text{MAIN UP} \\ \end{array} $ | → Position DOOR CLOSED ADJUSTMENT ADJUSTMENT ADJUSTMENT Save door position: Position DOOR CLOSED ADJUSTMENT ADJUSTMEN | | ⊕ and ⊙ > 2 sec. → INPUT DEUTSCH Scroll up through men Scroll up through me | FINE-UP (-1) (-1) (-1) (-1) (-1) (-1) (-1) (-1) (-1) (-1) (-1) (-1) (-1) | 0 < | τ ⊲ | AE OFF | FOREWARNING OFF OFF OFF OFF OFF OFF OFF OFF OFF OF | WOD6 | MOD1 | MOD14 | TLREST MODI | LEST* MOD2 | * | MOD1 | WO | REVERS- POINT 50 | LIGHTI PANN. 1 LB FUNC 1 MOD1 | | MOC | INPUT 2 A | INGTIME | | MOI | RESET MSBUS OFF | RY SET. | FIN NO.2 TITI SEPVICE DEF | |
|-----------|---|---|-----------|---|--|-----|-----|--------|--|------|------|-------|-------------|------------|---|------|----|------------------|----------------------------------|--|-----|-----------|---------|--|-----|-----------------|---------|------------------------------|--|
| P >1 sec. | SIMENT | DBY | P >1 sec. | | _ | | | | | | | | | | | | | | | | | | | | | | | U > 1 sec. | |
| | ADJUSTMENT | STANDBY | | | | | | | | | | | | | | | | | | | | | | | | | | | |

AUTOMATIC STANDBY

40



| | Scroll up through menu: (-) > 2 sec. Scroll down through menu: -) >2 sec. Return to AUTOMATIC mode: (-) >0nly queries are possible. |
|--|--|
| INVERTER MODI BRAKE F.OL. —250 BRAKE F.CL. —250 BRAKE P.CL. —250 SPEED UP OF. —210 SPEED UP MX —210 </td <td>UPPER SWITCH ON UPPER SWITCH ON LOWES SWITCH ON UP-SWITCH ON UP-SWITCH OF INPUT 1 OF SK5 -/ OF SK5 -/ OK SK6 -/ OK SK7 -/ OK SK6 -/ OK SK7 -/ OK SK8 -/ OK <</td> | UPPER SWITCH ON UPPER SWITCH ON LOWES SWITCH ON UP-SWITCH ON UP-SWITCH OF INPUT 1 OF SK5 -/ OF SK5 -/ OK SK6 -/ OK SK7 -/ OK SK6 -/ OK SK7 -/ OK SK8 -/ OK < |
| | DIAGNOSIS |
| | § . |



11. Overview of functions

11.1 Automatic operating mode



| Display | | Description |
|---------------------------|---|---|
| AUTOMATIC TEACH IN RUN | | Automatic teach-in of the running time |
| AUTOMATIC OPENING | | The door is in the opening phase. |
| AUTOMATIC CLOSING | | The door is in the closing phase. |
| AUTOMATIC STANDBY | | The door is at an intermediate position. |
| AUTOMATIC STANDBY | 0 | The door is at the OPEN end position. |
| AUTOMATIC STANDBY | 0 | The door is at the SECTSWITCH position ("INC.P.OP." parameter). |
| AUTOMATIC STANDBY | U | The door is at the CLOSED end position. |
| AUTOMATIC STANDBY | u | The door is at the SECTSWITCH position ("INC.P.CL." parameter). |
| AUTOMATIC STANDBY | r | The door is in the reversing switch-off position. |

If the "SELF LOCK" parameter is set to MOD2, 3, 4, 5 or MOD6 in the input menu, the display changes from AUTOMATIC to MANUAL.

| Display | Description |
|---------------------|--|
| MANUAL MAIN UP | The door is in the opening phase. |
| MANUAL MAIN DOWN | The door is in the closing phase. |
| MANUAL STANDBY | The door is at an intermediate position. |



11.2 Input operating mode



| Function | Description | Setting options | Factory settings |
|------------------|--|--|------------------|
| DEUTSCH | Select the menu language Only possible using the LCD monitor: Alternatively, the menu language can also be selected during the initialisation phase (during initial operation or after a reset). The menu language pre-set in the factory (DEUTSCH) appears here for approximately 60 seconds as flashing text in the display. At this point, the menu language can still be changed during the initialisation procedure. Pressing buttons [+] or [-] will allow you to scroll through and select a language. Save the language you have selected by pressing button [P]. After this, all texts or messages displayed are shown in the language that you have selected. | DEUTSCH ENGLISH FRANCAIS NEDERLANDS DANSK ESPANOL POLSKI CESKY ITALIANO SUOMI SVENSKA TÜRKÇE NORSK MAGYARUL | DEUTSCH |
| FINE-UP | Fine adjustment of the OPEN end position in relation to the saved OPEN end position (UPPER SWITCH). Only visible if an electronic end position system is used. | -250 — 250 | 0 |
| FINE-DOWN | Fine adjustment of the CLOSED end position in relation to the saved CLOSED end position (LOWER SWITCH). Only visible if an electronic end position system is used. | -250 – 250 | 0 |
| INC.P.OP | Setting the switching point for the intermediate OPEN position (SECTSWITCH) in relation to the saved OPEN end position. Displayed as a negative value. Only visible if an electronic end position system is used. Automatic teach-in of position: → "7.5 Setting the intermediate positions of the electronic end position system using the LCD monitor" | A (teach-in) -1 - LOWER SWITCH | A |
| INC.P.CL. | Setting the switching point for the intermediate CLOSE position (SECTSWITCH) in relation to the saved CLOSED end position. Displayed as a positive value. Only visible if an electronic end position system is used. Automatic teach-in of position: → "7.5 Setting the intermediate positions of the electronic end position system using the LCD monitor" | A (teach-in) 1 - UPPER SWITCH | A |
| OPEN TIME | After the door/gate has opened, it runs back automatically in the CLOSE direction after the set time has elapsed. Please note: If you press the CLOSE BUTTON during the open time, the closing run starts immediately. If you press the OPEN or STOP button during the open time, the time starts counting from the beginning again. If an automatic closing movement is interrupted by the SKS, the open time is added on with each new attempt. After 3 attempts, the automatic closing process will be aborted automatically. | OFF, 1 — 3600 s | OFF |
| START WARN. | The start warning is carried out before each run. | OFF, 1 — 10 s | OFF |
| FORE- WARNING | The forewarning is activated before an automatic closing run starts and before closing in impulse mode. | OFF, 1 – 300 s | OFF |
| | Please note: This time is added to the start warning. | | |



Overview of functions

| Function | Description | Setting options | Factory settings |
|-----------|--|---|------------------|
| AUT.CLOSE | Automatic closing after the open time has elapsed. MOD1: AUT.CLOSE from OPEN end position MOD2: AUT.CLOSE from SECTSWITCH end position MOD3: AUT.CLOSE from OPEN end position and SECTSWITCH end position MOD4: AUT.CLOSE from all door/gate positions | MOD1 – MOD4 | MOD1 |
| FAST CL. | Earlier closing after the photocell has been driven past. | OFF, | OFF |
| | Requirements: A photocell must be installed at passage height and an open time greater than 0 must have been programmed. | MOD2 – MOD4 | |
| | MOD2: The open time is cut short after the photocell (door closes immediately). MOD3: The open time is cut short after the photocell beam has been interrupted for a minimum of 2 seconds (in order to discount pedestrian traffic). MOD4: As for MOD2, except that the photocell has no function during the | | |
| | closing operation. | | |
| RELAY 1 | A relay mode from 1 - 13, 17 - 19, 21 - 41 and 60 - 62 can be assigned to all four relays. Relay 4 can also be programmed with MOD14 - 16. Further explanations: \rightarrow "Explanation of the relay modes:" on page 37 | MOD1 - MOD13 MOD17 - MOD19 MOD21 - MOD41 MOD60 - MOD62 | MOD6 |
| | MOD1: (Red traffic light 1) flashes during forewarning and is ON during door run* MOD2: (Red traffic light 2) flashes during forewarning and during door run* MOD3: (Red traffic light 3) is ON during forewarning and during door run* | | |
| RELAY 2 | MOD4: Impulse signal when OPEN command is given from inside MOD5: Error message MOD6: OPEN end position MOD7: CLOSED end position MOD8: OPEN end position negated | MOD1 - MOD13 MOD17 - MOD19 MOD21 - MOD41 MOD60 - MOD62 | MOD7 |
| | MOD9: CLOSED end position negated MOD10: Before-end position OPEN MOD11: Before-end position CLOSE | | |
| RELAY 3 | MOD12: Before-end position CLOSE to CLOSED end position MOD13: Magnetic lock function MOD14: Brake (normally energised mode) MOD15: Brake (normally de-energised mode) | MOD1 - MOD13 MOD17 - MOD19 MOD21 - MOD41 MOD60 - MOD62 | MOD1 |
| | MOD16: Brake (normally energised mode) switched on in OPEN end position MOD17: SKS activated or test error MOD18: (Red traffic light 4) flashes during forewarning and is OFF during door run MOD19: Before-end position OPEN to OPEN end position | | |
| RELAY 4 | MOD21: Test of draw-in protection before opening run (additional module required) MOD22: Activation of radio transmission systems 1 and 3 and/or light curtain testing MOD23: (Green traffic light) is ON at OPEN end position, OFF during forewarning and OFF during door run* | | MOD14 |
| | MOD24: Capacitor switching for 230 V/1~ sectional-door operators MOD25: Yard light function, light stays on for 2 minutes after OPEN impulse/command MOD26: Activation of radio 2 transmission system | | |
| | MOD27:Impulse signal when OPEN end position is reachedMOD28:Relay generally OFFMOD29:Door opensMOD30:Door closes | | |
| | MOD31: Service, continuous signal once the pre-set maintenance interval is reached MOD32: Battery mode MOD33: Battery operation not possible MOD34: Fixe alorg signal (fixe datastics and alorg system (RMA) active) | | |
| | MOD34: Fire alarm signal (fire detection and alarm system (BMA) active) MOD35: Photocell operative MOD36: Wicket door locking cylinder MOD37: Testing of stop signal through radio transmission systems 1 and 3 | | |
| | MOD38: Testing of light curtain 2 (input 2) MOD39: LED error MOD40: Impulse signal when OPEN command is given from outside MOD41: Test of radio transmission system 4 in OPEN direction | | |



| G | B |
|---|---|
| | |

| Function | Description | Setting options | Factory settings |
|------------------|--|----------------------------------|------------------|
| | MOD60: (Red traffic light, outside) flashes during forewarning and is ON during | | |
| | door run MOD61: (Red traffic light outside) flashes during forewarning and during door run MOD62: (Green traffic light outside) ON at OPEN end position, OFF during forewar- ning, and OFF during door run) | | |
| | * If two-way traffic control is activated: TRAFFIC LIGHT INSIDE | | |
| TL REST | Switches traffic lights MOD1: OFF in standby mode MOD2: ON in standby mode MOD3: In standby OFF after 5 minutes | MOD1 – MOD3 | MOD1 |
| SKS | MOD1: OSE (optosensor) MOD2: 8.2 kΩ (electrical contact strip) MOD3: DW Pressure sensor (airwave bar) as NC with testing MOD4: Light curtain OSE MOD5: Light curtain PNP | A — self teach-in MOD1 — MOD5 | A |
| | NOTICE: MOD4 and MOD5 must be set manually if a light curtain is used. Without any addition to the open time (if programmed) after the light curtain has been interrupted during automatic closing. Without switching off "Automatic closing" after 3 interruptions in a row. | | |
| DW TEST | Activation and deactivation of testing function for the attached DW airwave bar. Only appears if parameter setting SKS = MOD3. MOD1: Test OFF MOD2: Test ON | MOD1 – MOD2 | MOD2 |
| DW-POINT | Point at which the DW airwave bar attached is tested (X4 / 5+6). Only appears if parameter setting SKS = MOD3. Setting is done in increments (only AWG), starting from the lower travel cut-out point. In systems with mechanical limit switches, the additional CLOSE limit switch serves as the DW-POINT. | 0 – 1000 | 20 |
| SKS FUNC | MOD1: Stop + reverse MOD2 Stop + 2-second reversing movement | MOD1 – MOD2 | MOD1 |
| SKS REV | MOD1: Stop + reverse Stop between OPEN end position and reversing point between reversing point and CLOSED end positi- on on → for vertically closing doors MOD2 Stop + reverse between OPEN end position and reversing point | MOD1 – MOD3 | MOD1 |
| | No action between reversing point and CLOSED end positi- on → for vertically closing doors with leading photocell | | |
| | MOD3: Stop + reverse between OPEN end position and CLOSED end position → for horizontally closing doors and systems with mechanical limit swit- ches without pre-limit switch | | |
| | NOTICE: In systems with mechanical limit switches, the additional CLOSE limit switch serves as the reversing point. | | |
| REVERS- POINT | Reversing point. Point at which the reversing movement of the door is switched off. Appears only for systems with an electronic end position system (AWG). Setting is done in increments, starting from the lower travel cut-out point. In systems with mechanical limit switches, the additional CLOSE limit switch serves as the reversing point. | A — self teach-in 1 — 1000 | 50 |



Overview of functions

| Function | Descrip | tion | | Setting options | Factory settings |
|-------------|--|--|---|----------------------------------|------------------|
| LIGHT BARR. | Photocell 1, installed in the drive-through area of the door. Connection to X4 / 1-4 | | A – self teach-in MOD1 – MOD3 | A | |
| | MOD1: MOD2: MOD3: | MFZ 2-wire system NC contact / NPN PNP | | | |
| LB FUNC 1 | Function o | Function of photocell 1 in the drive-through area of the door. | | MOD1 – MOD9 | MOD1 |
| | MOD1: MOD2: MOD3: MOD4: MOD5: MOD6: MOD7: MOD8: MOD9: | CLOSING door movement Stop + reverse Stop + short reversal STOP STOP Stop + reverse No action No action No action Dragging up suppression (Door OPENING movement not the photocell is no longer inter | No action No action No action STOP Dragging up suppression (Door OPENING movement not possible until the photocell is no longer inter- rupted). Stop + reverse Stop + short reversal Stop Stop + reverse t possible until | | |
| LB FUNC 2 | Only appe Connectio | of photocell 2 in the drive-through ears if parameter setting INPUT 1 = on only possible as an NC contact mode similar to the settings under | = MOD15. at programmable Input 1 (X4 / 9+10). | MOD1 - MOD9 | MOD1 |
| PEB POINT | POINT. Set visible in s Please n e | tting is done in increments, startin systems with electronic limit switc ote: When adjusting, this point w | reen the CLOSED end position and the PEB g from the lower travel cut-out point. Only h. ill be automatically recognised during 1 is installed in the door frame and the | A — teach-in 1 - UPPER SWITCH | A |
| | photocell | | osing operation from this point through to | | |
| IMPULSE | Select a function to be assigned to the impulse button (X3 / 7+8). | | | MOD1 – MOD5 | MOD1 |
| | MOD1: MOD2: MOD3: MOD4: MOD5: | OPEN - STOP - CLOSE - STOP - OPEN if door is stationary / No Stop and OPEN if door is closin OPEN if door is stationary / STO OPEN if door is stationary / No OPEN if door is stationary / CLO | action if door ⁱ s opening 1g DP if door is moving | | |



| Function | Description | Setting options | Factory settings |
|-------------|---|--------------------------|------------------|
| NPUT 1 | Select a function to be assigned to Input 1 (X4 / 9+10). | MOD1 – MOD17 | MOD1 |
| | MOD1: SECTSWITCH button | MOD30 – MOD32 | |
| | MOD2: SECTSWITCH switch | | |
| | MOD3: AUTO CLOSE switch | | |
| | MOD4: External CLOCK (continuously OPEN) MOD5: Fire alarm (BMA) switch 3 (partial opening) NO | | |
| | MOD6: Fire alarm (BMA) switch 1 (emergency closing) NO | | |
| | MOD7: Fire alarm (BMA) switch 1 (emergency closing) NC | | |
| | MOD8: Fire alarm (BMA) switch 2 (emergency opening) NO MOD9: Fire alarm (BMA) switch 2 (emergency opening) NC | | |
| | MOD9. File alarm (binA) switch 2 (energency opening) NC MOD10: Ventilation button (partial opening) NO | | |
| | MOD11: Automatic closing button | | |
| | MOD12: Laser scanner (special solution) | | |
| | MOD13: Fire alarm (BMA) switch 3 (partial opening) NC MOD14: Wicket door lock | | |
| | MOD15: Photocell 2 NC | | |
| | MOD16: Forewarning switch | | |
| | MOD17: Impulse button MOD30: OPEN button inside | | |
| | MOD31: OPEN button outside | | |
| | MOD32: CLOSE button (Only active with operational closing edge safety device | | |
| | and operational Photocell 1. No function in deadman mode.) | | |
| NPUT 2 | Select a function to be assigned to Input 2 (X4 / 11+12). | A — self teach-in OFF | MOD1 |
| (SKS2) | OFF: NOT active | MOD2 - MOD7 | |
| | MOD2: Wicket door switch 8.2 k Ω | | |
| | Stop if there is deviation | | |
| | MOD3: Closing edge safety device OPEN 8.2 k Ω , active in the OPEN direction Stop and reverse when triggered | | |
| | MOD4: Closing edge safety device 8.2 kΩ, active in the OPEN direction | | |
| | Stop and short reversal when triggered | | |
| | MOD5: Battery mode MOD6: Radar motion detectors (special solution) | | |
| | MOD7: Light curtain 2 (PNP) | | |
| | During initial operation and after a reset, Input 2 will be set once to $A -$ self teach- | | |
| | in. If no connected components are recognised, the input will be automatically deactivated. OFF appears in the display and the input must be manually activated. | | |
| | ueactivateu. On appears in the display and the input must be manually activateu. | | |
| SKS3 | Setting for Channel 1 of the plug-in signal transmission system (X20). | MOD1 - MOD4 | MOD1 |
| | MOD1: not active | | |
| | MOD2: Activated as closing edge safety device in the CLOSING direction. MOD3: Activated as closing edge safety device in the OPENING direction. | | |
| | MOD4: Activated as safety device (internal safety circuit) | | |
| SCS4 | Setting for Channel 2 of the plug-in signal transmission system (X20). | MOD1 - MOD4 | MOD1 |
| | Selection mode similar to the settings under SKS 3. | | |
| RUNNING- | Monitoring the maximum running time for an OPEN or CLOSE movement. | A – self teach-in | А |
| TIME | The running time is determined automatically during the teach-in run. In the event of a 20% deviation (in both directions) an ERROR RUNTIME appears. | OFF | |
| | After the automatic teach-in, the running time can be manually changed. | 1 — 300 s | |
| | | | |
| REVERS.TIME | Motor stoppage time each time the door changes direction. | 100 - | 300 ms |
| | When the closing edge safety device is triggered during the closing movement, the reversal time amounts to a quarter of the programmed time. | 5000 ms | |
| | reversar time amounts to a quarter of the programmed time. | | |



Overview of functions

| Function | Description | Setting options | Factory settings |
|----------------|--|---------------------------------------|------------------|
| LIMIT SW. | Select the end position system to be evaluated. | A – self teach-in MOD1 – MOD4 | A |
| | MOD1: Absolute value encoder (AWG) MOD2: Mechanical limit switch (MEC) MOD4: AWG with negative impulses (Only for frequency converter operation with anticlockwise rotating field) | | |
| SELF LOCK | Choose between impulse and manual operation, with or without evaluation of closing edge safety device (CESD) and photocell system (LB). | MOD1 – MOD6 | MOD1 |
| | MOD1: Impulse operation for OPEN + CLOSE with SKS and LB MOD2: Manual operation for OPEN + CLOSE with SKS and LB MOD3: Manual operation for CLOSE with SKS and LB MOD4: Manual operation for OPEN with SKS and LB MOD5: Manual operation for OPEN + CLOSE without SKS and LB MOD6: Manual operation for CLOSE without SKS and LB | | |
| POWER | Automatic power monitoring (monitoring the rotational speed) Error message if the door/gate is unable to move freely or is obstructed. Setting the sensitivity for the OPEN direction of travel. A reading giving the power value (rotational speed) is shown during opening runs. If the power monitoring facility is activated, a value must be set that is lower than the lowest value displayed during door/gate travel. The larger the difference compared to the lowest value displayed, the less sensitively the power monitoring reacts. The power monitoring is only activated if a numerical value is set. | OFF 1 – 999 | 10 |
| RESET MSBUS | All MSBUS addresses assigned will be reset. After restarting the control, all MSBUS devices connected will be re-addressed. \rightarrow Refer to the instruction manual for the MSBUS device for detailed information. | ON OFF | OFF |
| RESTART | Control is restarted if function is activated. | ON OFF | OFF |
| FACTORY SET. | Selecting the set of parameters that you want to reset to.MOD7:MEZ S→ Operators of the STAW range with increased duty cycleMOD8:MFZ FU→ Operators of the MTZ 05 rangeMOD9:MFZ FU→ Operators of the STA rangeMOD99:MFZ S→ StandardMOD10 - MOD 98:Customer-specific parameter sets | MOD7 - MOD9 MOD10 - MOD98 MOD99 | MOD9 |
| RESET | Reset the control parameters to the pre-set factory settingsMOD2:Partial reset 1 (everything except the frequency converter settings)MOD3:Partial reset 2 (everything except the end positions / end positionsystem)MOD4:MOD4:Total reset (everything is returned to factory default setting) | OFF, MOD2 - MOD4 | OFF |
| PIN NO. 2 | Input and selection of a PIN code for programming a maintenance interval. After entering the PIN code, the second programming level is opened. A maintenance interval can now be input at the parameter SERVICE. Input level 2 goes off again after the power has been switched off, or goes off automatically after 10 minutes. The PIN code can only be changed at the second programming level. | 0 — 9999 | 1111 |
| SERVICE | OFF: Maintenance indicator not activated Setting a maintenance interval. After the pre-set number of door cycles has been carried out, a maintenance message (LED / LCD) is given. If a relay output is program- med to MOD31, the relay concerned is triggered (continuous signal). Only appears after input level 2 has been activated via parameter PIN NO. 2. | OFF 0 – 99999 | OFF |



| Function | Description | Setting options | Factory settings |
|------------------|--|--|------------------|
| INVERTER | Activates or deactivates a connected frequency converter. If a frequency converter is connected at the X18 interface, the control becomes a CS 310 FU control. | MOD1 – MOD3 | MOD1 |
| | MOD1:Operation without frequency converterMOD2:Operation with frequency converterMOD3:Operation with frequency converter (effective ramp times) | | |
| BRAKE P.OP.* | Initiates the deceleration time SLOW DO. OP. Display in absolute value encoder increments as a negative value in relation to the upper end switch-off point. <i>Only applies for OPENING direction of door travel.</i> | -999 — 0 | -250 |
| BRAKE P.CL.* | Initiates the deceleration time SLOW DO. CL. Display in absolute value encoder increments as a positive value in relation to the lower end switch-off point. <i>Only applies for CLOSING direction of door travel.</i> | 0 – 999 | 250 |
| BRAKE P.CL.2* | Initiates the delay time DO. MX. Display in absolute value encoder increments as a positive value in relation to the lower end switch-off point. If the end positions are changed again (e.g. fine adjustment), the BP2 is deactivated again (display A) and must be re-programmed. Only applies for CLOSING direction of door travel. | 0 - UPPER SWITCH (0 - LOWER SWITCH) | A |
| | * Parameters appear only after programming the end positions | | |
| SPEED OPEN | Normal speed for OPENING door movement. | MOT.HZ MIN - MAX | 50 Hz |
| SPEED CLOSE | Normal speed for CLOSING door movement. | MOT.HZ MIN - MAX | 50 Hz |
| MX SPEED CL. | Maximum speed for CLOSING door movement (optional). Parameter appears only after programming BRAKE P. CL.2. | Mot.Hz Min - Max | 50 Hz |
| SOFTRUN OP. | Minimum speed for OPENING door movement. | MOT.HZ MIN - 50 Hz | 25 Hz |
| SOFTRUN CL. | Minimum speed for CLOSING door movement. | MOT.HZ MIN - 50 Hz | 25 Hz |
| SPEED UP OP. | Acceleration time between starting command and SPEED OPEN frequency. Only applies for OPENING direction of door travel. | 0.1 – 9.9 s | 2.0 s |
| SPEED UP CL. | Acceleration time between starting command and SPEED CLOSE frequency. Only applies for CLOSING direction of door travel. | 0.1 – 9.9 s | 2.0 s |
| slow do. op. | Deceleration time between Brake point OPEN and SOFTRUN OP. frequency Only applies for OPENING direction of door travel. | 0.1 – 9.9 s | 2.0 s |
| SLOW DO. CL. | Deceleration time between Brake point CLOSE and SOFTRUN CL. frequency Only applies for CLOSING direction of door travel. | 0.1 – 9.9 s | 2.0 s |
| SPD. UP MX * | Acceleration time between starting command and MX SPEED CL. frequency. Only applies for CLOSING direction of door travel. | 0.1 — 5.0 s | 2.0 s |
| SLO. DO. MX * | Deceleration time between Brake point CL2 and SPEED CLOSE frequency. Only applies for CLOSING direction of door travel. | 0.1 — 5.0 s | 2.0 s |
| | * Parameters appear only after programming Brake point CL.2. | | |
| SPEED UP SKS | Acceleration time after reversal of direction until SPEED OPEN/CLOSE frequency. Applies for both directions of door/gate travel and activation of closing edge safety device. | 0.1 – 1 s | 0.5 s |



Overview of functions

| Function | Description | Setting options | Factory settings |
|------------------|--|------------------------------|------------------------|
| SLOW DO. SKS | Delay time between activating the SKS closing edge safety device and stopping the system. Applies for both directions of door/gate travel and activation of closing edge safety device. | 0.1 – 1 s | 0.1 s |
| SPEED UP LB | Acceleration time after reversal of direction until SPEED OPEN/CLOSE frequency. Applies for both directions of door/gate travel and activation of photocell. | 0.1 – 5.0 s | 0.5 s |
| SLOW DOWN LB | Delay time between activating the photocell and stopping the system. Applies for both directions of door/gate travel and activation of photocell. | 0.1 – 5.0 s | 0.5 s |
| SLOW DO. STOP | Delay time between the stop command / reaching an end position and stopping the system. Applies for both directions of door/gate running. | 0.0 – 5.0 s | 0.5 s |
| RES.INVERTER | Resets all parameters of the frequency converter (factory default setting). | ON OFF | OFF |
| MOTOR V | Nominal motor voltage. | 100 - 500 V | 230 V |
| MOTOR I | Nominal motor current. | 1 – 9.9 A | 5.1 A |
| MOTOR P | Nominal motor current. | 100 – 5000 W | 550 W |
| MOTOR PHI | Motor power factor (cosine phi). | 0 – 1 | 0.69 |
| MOTOR HZ | Nominal motor frequency. | 10 – 100 Hz | 50 Hz |
| MOTOR RPM | Nominal motor rpm. | 100 — 5000 min ⁻¹ | 1370 min ⁻¹ |
| Motor Hz Min | The minimum value to which the operating frequency of the motor can be set. | 10 – 50 Hz | 10 Hz |
| MOT.HZ MAX | The maximum value to which the operating frequency of the motor can be set. | 50 – 100 Hz | 87 Hz |
| BRAKE DELAY | Causes delayed brake release following a starting command. Prevent the door/gate from sagging when it starts from an intermediate position. | 0 - 500 ms | 50 ms |



Explanation of the relay modes:

A. Traffic light functions

| MOD | Description | CLOSED end position | OPEN end position | Forewarning | Door run |
|-------|----------------------------------|-----------------------|-------------------|-------------|----------|
| MOD1 | Red traffic light 1 ³ | ON / OFF ¹ | OFF ² | Flashing | Lit up |
| MOD2 | Red traffic light 2 ³ | ON / OFF ¹ | OFF ² | Flashing | Flashing |
| MOD3 | Red traffic light 3 ³ | ON / OFF ¹ | OFF ² | Lit up | Lit up |
| MOD18 | Red traffic light 4 ³ | OFF | OFF | Flashing | OFF |
| MOD23 | Green traffic light 3 | OFF | ON ² | OFF | OFF |
| MOD60 | Red traffic light 1 4 | ON / OFF ¹ | OFF ² | Flashing | Lit up |
| MOD61 | Red traffic light 2 ⁴ | ON / OFF ¹ | OFF ² | Flashing | Flashing |
| MOD62 | Green traffic light ⁴ | OFF | ON ² | OFF | OFF |
| | 1 | 1 | | | |

¹ Dependent on parameter TL REST

² If two-way traffic control is activated: dependent on inside or outside OPEN command

³ If two-way traffic control is activated: traffic light inside

⁴ If two-way traffic control is activated: traffic light outside

B. Position messages

| MOD | Description | Remarks |
|-------|---|--|
| MOD6 | OPEN end position | The relay closes the contact when the door is at the OPEN end position. |
| MOD7 | CLOSED end position | The relay closes the contact when the door is at the CLOSED end position. |
| MOD8 | Not OPEN end position | The relay closes the contact when the door is not at the OPEN end position. |
| MOD9 | Not CLOSED end position | The relay closes the contact when the door is not at the CLOSED end position. |
| MOD10 | Intermediate OPEN position (SECTSWITCH) | The relay closes the contact when the door is at the intermediate OPEN position (SECTSWITCH). |
| MOD11 | Intermediate CLOSED position (SECTSWITCH) | The relay closes the contact when the door is at the intermediate CLOSE position (SECTSWITCH). |
| MOD12 | Intermediate CLOSED position to CLOSED end position | The relay closes the contact when the door is in the area between the CLOSED end position and the intermediate CLOSED position (SECTSWITCH). |
| MOD19 | Intermediate OPEN position to OPEN end position | The relay closes the contact when the door is in the area between the OPEN end position and the intermediate OPEN position (SECTSWITCH). |



C. Impulse signals

| MOD | Description | Remarks |
|--------|---|--|
| MOD4 | Impulse when OPEN command is given from inside | The relay closes the contact for 1 second when the door receives an OPEN command from inside. This impulse can be used to control lights, for instance. |
| MOD27 | Impulse when OPEN end position is reached | The relay closes the contact for 2 seconds when the door reaches the OPEN end position. This impulse can be used, for instance, to open a following photocell. |
| MOD 40 | Impulse when OPEN command is given from outside | The relay closes the contact for 1 second when the door receives an OPEN command from outside. This impulse can be used to control lights, for instance. |

D. Brake functions (only adjustable on relay 4)

| MOD | Description | Remarks |
|-------|---|--|
| MOD14 | Brake (normally energised mode) | The switching contact of the brake rectifier is activated via the relay to achieve a faster brake function. As soon as the door starts to move, the contact closes and the brake is released (normally energised mode). |
| MOD15 | Brake (normally de-energised mode) | The switching contact of the brake rectifier is activated via the relay to achieve a faster brake function. As soon as the door starts to move, the contact opens and the brake is released (normally de-energised mode). |
| MOD16 | Brake (normally energised mode) switched on in OPEN end position | The switching contact of the brake rectifier is activated via the relay to achieve a faster brake function. As soon as the door starts to move, the contact closes and the brake is released (normally energised mode). In order to stop the door/gate more smoothly at the OPEN end position, the switching contact is not switched at the OPEN END POSITION (OPEN TIME). |

E. Error messages

| MOD | Description | Remarks |
|-------|-------------------------------------|---|
| MOD5 | Error message | The relay opens the contact when a STOP command is given or an error occurs. All errors described in Section 10 result in actuation of the relay. |
| MOD17 | Closing edge safety device actuated | The relay opens the contact when the closing edge safety device is actuated. An error in the closing edge safety device or an unsuccessful test is shown via MOD5. |
| MOD35 | Photocell | As with photocell input X4 (3/4), the signal received is passed on in the form of a message. Relay ON: Photocell signal is OK Relay OFF: Light beam interrupted or fault in photocell |
| MOD39 | LED error | The relay always closes the contact when the internal error LED 2 (red) lights up. |



F. Movement signal

| MOD | Description | Remarks |
|-------|--------------|-------------------------|
| MOD29 | Door OPENS. | Active during movement. |
| MOD30 | Door CLOSES. | Active during movement. |

G. Functions for external accessories

| MOD | Description | Remarks |
|--------|---|--|
| | · · | |
| MOD13 | Magnetic lock function | The relay closes before each door movement. The relay is normally open. A delay of 0.5 seconds is programmed to elapse before each door movement takes place. |
| MOD21 | Test of draw-in protection | The relay generates a test signal when the CLOSED end position is reached and expects, as a reaction to the test signal, that the stop circuit is actuated. |
| MOD22 | Activation of radio transmission systems 1 and 4, testing of light curtain 1 | The relay generates a test signal when the OPEN end position is reached and expects, as a reaction to the test signal, that the closing edge safety device input is actuated. |
| MOD24 | Capacitor | Whenever a door movement command is given, the relay closes for approximately 1 second. With the aid of this relay, an additional starting capacitor that is required for AC applications is switched on, to ensure safe starting of the motor. For operators of the STAW range with increased duty cycle. |
| MOD25 | Yard light function | At every OPEN command, the relay is closed for 2 minutes and can therefore be used to control a light. |
| MOD26 | Activation of radio transmission systems 2 and 4 | Before every CLOSE command, the radio transmission system is activated by an impulse. The duration of the activation must be set on the transmission system. This activation results in a 0.5 second delay in starting. |
| MOD28 | Relay OFF | The relay is generally switched off; the contact is always open. |
| MOD36 | Pneumatic cylinder for locking the wicket door (threshold-less door system). | Every time an OPEN command is given, the relay is activated and controls a pneuma- tic cylinder which mechanically locks the wicket door that is incorporated in the door. The locking position of the cylinder is queried through a limit switch. The door starts moving only after this limit switch has been released. The relay remains activated until the lower end position has been reached again. |
| MOD37 | Testing of the stop signal via radio transmission systems 1 and 3 | The relay generates a test signal when the OPEN end position is reached and expects, as a reaction to the test signal, that the stop circuit is interrupted. |
| MOD38 | Testing light curtain 2 (8.2 k Ω) Connection to input 2 (X4 / 11+12) | The relay generates a test signal when the OPEN end position is reached and expects, as a reaction to the test signal, that there is an interruption to Input 2. |
| MOD 41 | Activation of radio transmission system 4 in the OPEN direction | The relay generates a test signal when the CLOSED end position is reached and expects, as a reaction to the test signal, that there is an interruption to Input 2. |
| | OPEN direction | expects, as a reaction to the test signal, that there is an interruption to Input 2. |



H. Input-dependent messages

| MOD | Description | Remarks |
|-------|---------------------|---|
| MOD32 | Battery mode | Active during battery operation. Input 2 bridged (setting MOD5). |
| MOD33 | Not in battery mode | Active during mains operation. Input 2 open (setting MOD5). When programmed with MOD32/33, the relays work as delayed change-over contacts and follow the signal at Input 2 if set to MOD5. In this case, input 2 is supplied with a control signal from the uninterruptible power supply (UPS) system which is responsible for switching between mains power and the UPS power supply. |
| MOD34 | BMA signal | Triggered if fire alarm system (BMA) active. Follows the signal at Input 1 if set to MOD5-9 / 13. In this case, Input 1 is supplied with a control signal from the fire alarm system, and depending on the setting, opens or closes the door to an end position or an intermediate position. |

Key to inputs:

A. Input 1 functions

| MOD | Description | Remarks |
|------|---|---|
| MOD1 | SECTSWITCH button | When the button is pressed (Input 1), the door opens as far as the intermediate OPEN position (SECT SWITCH). |
| MOD2 | SECTSWITCH switch | Closed: All OPEN commands lead to the intermediate OPEN position (SECTSWITCH). Open: All OPEN commands lead to the OPEN end position. |
| MOD3 | AUTO CLOSE switch | Closed: No automatic closing (open time continues, if open time > 0) Open: Automatic closing run is activated (if open time > 0) |
| MOD4 | External CLOCK (continuously OPEN) | The door opens once the contact closes and remains in the OPEN position (open time continues) until the contact opens. The door then closes automatically (only if open time $>$ 0) This function can be aborted by pressing the CLOSE button. The gate CLOSES. |
| MOD5 | Fire alarm (BMA) switch 3 (partial opening) NO | Control function if fire alarm system is active. Open: Normal operation Closed: Partial opening of the door. The intermediate OPEN position (SECTSWITCH) is approached from either direction, irrespective of the current door position. |
| | | BUTTON: No function LIGHT BARR / SKS: Door stops and briefly reverses (only in CLOSING direction), and closes again after 5 seconds STOP: Emergency closing interrupted as long as this is activated |
| MOD6 | Fire alarm (BMA) switch 1 (emergen- cy closing) NO | Control function if fire alarm system is active. Open: Normal operation Closed: Emergency closing of door |
| | | BUTTON: No function LIGHT BARR / SKS: Door stops and briefly reverses; emergency closing again after 5 seconds |
| | | STOP: Emergency closing interrupted as long as this is activated |



| | Description | Remarks | |
|--|---|--|--|
| MOD7 Fire alarm (BMA) switch 1 (emergen- cy closing) NC | | Control function if fire alarm system is active. Closed: Normal operation Open: Emergency closing of door | |
| | | BUTTON: No function LIGHT BARR / SKS: Door stops and briefly reverses; emergency closing again after 5 seconds | |
| | | STOP: Emergency closing interrupted as long as this is activated | |
| MOD8 | Fire alarm (BMA) switch 2 (emergency opening) NO | Control function if fire alarm system is active. Open: Normal operation Closed: Emergency opening of door | |
| | | BUTTON: No function LIGHT BARR / SKS: No function STOP: Emergency closing interrupted as long as this is activated. No automatic closing after deactivation of fire alarm signal. | |
| MOD9 | Fire alarm (BMA) switch 2 (emergency opening) NC | Control function if fire alarm system is active. Closed: Normal operation Open: Emergency opening of door | |
| | | BUTTON: No function LIGHT BARR / SKS: No function STOP: Emergency closing interrupted as long as this is activated. No automatic closing after deactivation of fire alarm signal. | |
| MOD10 | Ventilation button NO | Partial opening of the door. When an additional button at Input 1 is pressed, the intermediate CLOSE position (SECTSWITCH) is approached from either direction, irrespective of the current door position. | |
| MOD11 | "Automatic closing" button | 1st activation:No automatic closing; the open time continues.2nd activation:Automatic closing of the door is active again, if the open time is > 0.3rd activation:No automatic closing; the open time continues | |
| MOD12 | Laser scanner (height detection) | Only in conjunction with Input 2 (MOD 6). \rightarrow See explanation regarding Input 2. | |
| MOD13 | Fire alarm (BMA) switch 3 (partial opening) NC | Control function if fire alarm system is active. Closed: Normal operation Open: Partial opening of the door. The intermediate OPEN position (SECTSWITCH) is approached from either direction, irrespective of the current door position. | |
| | | BUTTON: No function LIGHT BARR / SKS: Door stops and briefly reverses (only in CLOSING direction), and closes again after 5 seconds STOP: Emergency closing interrupted as long as this is activated. | |
| MOD14 | Wicket door lock | Monitoring limit switch for the pneumatic lock system for wicket doors. The limit switch must confirm correct locking within 10 seconds of an OPEN command being given, otherwise the door remains stationary and an error message is given. This function affects relay mode 36. | |
| MOD15 | Photocell 2 NC | If a second photocell is installed in the drive-through area of the door, this system can be programmed via the LB FUNC 2 parameter in INPUT mode. Only photocells with a potential-free NC contact may be connected. | |
| MOD16 | Forewarning switch | Closed: Start-up warning and forewarning are inactive (even if both times are > 0). Open: Start-up warning and forewarning are active (only when both times are > 0). | |



| MOD | Description | Remarks |
|-------|------------------------|--|
| MOD17 | Impulse button outside | Pressing the button moves or stops the door. The function and direction of the movement depend on the IMPULS parameter setting in the Input menu. → "11.2 Input operating mode" on page 29 If two-way traffic control is activated, this impulse command is treated as a signal from outside. |
| MOD30 | OPEN button inside | When the button is pressed, the door opens as far as the OPEN end position. The traffic light inside changes to green. |
| MOD31 | OPEN button outside | When the button is pressed, the door opens as far as the OPEN end position. The traffic light outside changes to green. |
| MOD32 | CLOSE button | When the button is pressed, the door closes as far as the CLOSED end position. Only active with operational closing edge safety device and operational photocell 1. No function in deadman mode. |

B. Input 2 functions

| MOD | Description | Remarks |
|------|---|--|
| OFF | | not active |
| MOD2 | Wicket door switch (8.2 k Ω) | Generally active Stops the system when actuated. |
| MOD3 | Closing edge safety device OPEN (8.2 $k\Omega)$ | Closing edge safety device active in the OPENING direction Door stops and reverses to the CLOSED end position when the closing edge safety device is triggered. |
| MOD4 | Closing edge safety device OPEN (8.2 $k\Omega)$ | Closing edge safety device active in the OPENING direction Door stops and moves in the CLOSE direction for 2 seconds (short reverse) when the closing edge safety device is triggered. |
| MOD5 | Battery operation (MDFU special solution) n.o. | Active if power supplied by battery. Relay switching MOD32 / MOD33. |
| MOD6 | Radar motion detector (height detection) NO | The function is coupled to Input 1 (MOD12 – laser scanner). The preceding laser scanner detects the height of the vehicle. The installed radar motion detector generates an OPEN command when actuated. A tall vehicle (lorry) will be detected by the laser scanner. The laser scanner switches Input 1 (MOD12) to ON. The radar motion detector evaluates the vehicle and triggers the door movement. The door is moved to the OPEN end position. A lower vehicle (car) is recognised by the laser scanner. The laser scanner switches Input 1 (MOD12) to OFF. The radar motion detector evaluates the vehicle and triggers the door movement. The door is moved to the intermediate OPEN position (SECTSWITCH). All other OPEN commands (via X3, X7, X9, X13) always move the door to the OPEN end position. The Input 1 function (MOD12) then has no effect. |
| MOD7 | Light curtain 2 (PNP) | Acts in same way as light curtain 1 (SKS MOD 4+5) – Light curtain active in the CLOSE direction. – Stop and reverse when the light curtain is triggered. The type of reversing (reverse / short reversal) is also adopted. |



11.3 Diagnosis / error memory operating mode



GB

| Display | Meaning | Status |
|--------------|--|--|
| UPPER SWITCH | OPEN end position | OFF: End position reached ON: End position not reached |
| LOWER SWITCH | CLOSED end position | OFF: End position reached ON: End position not reached |
| OPEN BUTTON | Command button / OPEN input | ON: Button activated / input is active OFF: Button not activated / input not active |
| CLOSE BUTTON | Command button / CLOSE input | ON: Button activated / input is active OFF: Button not activated / input not active |
| INPUT 1 | INPUT 1 (X4 / 9 + 10) | ON: Input 1 active OFF: Input 1 not active |
| INPUT 2 | INPUT 2 (X4 / 11 + 12) | ON: Input 2 active OFF: Input 2 not active Display ON / OFF only if set to MOD5 / MOD6 in parameter INPUT 2. |
| SKS | Closing edge safety device 1 (PS switch, $8.2k\Omega$ or optosensor) or light curtain 1 (PNP or optosensor) (X4 / 5-8) CLOSING direction | ON: System closed OFF: System interrupted (fault) |
| SKS 2 | Closing edge safety device 2 (8.2 k Ω) or light curtain 2 (PNP) Connection to Input 2 (X4 / 11+12) OPEN direction | ON: System closed OFF: System interrupted (fault) Display ON / OFF only if set to MOD3 / MOD4 / MOD7 in parameter INPUT 2. |
| STOP 2 | Safety circuit 2 Wicket door switch (8.2 k Ω) Connection to INPUT 2 (X4 / 11+12) | ON: Safety circuit closed OFF: Safety circuit interrupted (fault) Display ON / OFF only if set to MOD2 in parameter INPUT 2. |
| SKS 3 | Closing edge safety device 3 (8.2k Ω or optosensor) Radio transmission system channel 1 OPEN or CLOSE direction | ON: System closed OFF: System interrupted (fault) Display ON / OFF only if set to MOD2 / MOD3 in parameter SKS 3. |
| STOP 3 | Safety circuit 3 Radio transmission system channel 1 | ON: Safety circuit closed OFF: Safety circuit interrupted (fault) Display ON / OFF only if set to MOD4 in parameter SKS 3. |
| SKS 4 | Closing edge safety device 4 (8.2k Ω or optosensor) Radio transmission system channel 2 OPEN or CLOSE direction | ON: System closed OFF: System interrupted (fault) Display ON / OFF only if set to MOD2 / MOD3 in parameter SKS 4. |
| STOP 4 | Safety circuit 4 Radio transmission system channel 2 | ON: Safety circuit closed OFF: Safety circuit interrupted (fault) Display ON / OFF only if set to MOD4 in parameter SKS 4. |
| IMPULS | Command button / IMPULSE input (X3 / 7+8) | ON: Button activated / input is active OFF: Button not activated / input not active |
| | | |



| Display | Meaning | Status |
|-------------------------|--|---|
| SWITCH CLOCK | Weekly timer (pluggable) | ON: Timer activated OFF: Timer not activated |
| LIGHT BARR. | Drive-through photocell 1 (X4 / 1-4) | ON: Photocell signal is OK OFF: Light beam interrupted or fault in photocell |
| LIGHT BARR. 2 | Drive-through photocell 2 Connection to Input 1 (X4 / 9+10) | ON: Photocell signal is OK OFF: Light beam interrupted or fault in photocell |
| SAFETY CIRC. | Safety circuit 1 Emergency stop systems of door system | ON: Safety circuit closed OFF: Safety circuit interrupted |
| STOP | STOP command button (keypad on cover) | ON: Button not activated OFF: Button activated |
| ROT FIELD | Shows currently set rotational direction of door operator | RIGHT: Setting for clockwise rotating field LEFT: Setting for anticlockwise rotating field |
| CYCLE | Door cycle counter | Displays number of door cycles counted so far 1 x OPEN + 1 x CLOSE = 1 cycle Counts only if the travel cut-out points are reached. |
| SERVICE | Service alarm function Service alarm function parameters SERVICE and PIN NO. 2 | OFF: Maintenance indicator not activated 0 - 99999: Maintenance indicator activated Displays the number of door cycles left until a maintenance message is sent |
| AWG | Shows position information of absolute value encoder | Displays the current transmitted value |
| ERROR COUNT CYCLE | Control unit error memory Error messages from the control unit can be read out here with information on the frequency and cycle. The list of error messages can be scrolled through using buttons [+] and [-] on the LCD monitor. → "12.1 Error message shown on LCD display" Deleting the error log: Press buttons [+] and [-] at the same time for approximately 2 seconds. Every error message must be individually deleted. | The display changes every 2 seconds to show the following in turn: – the error description, – the frequency of occurrence and – the cycle in which the error last occurred. If the quantity given under "Count" is 0, this means that this particular error has never occurred before. |



12. Error messages and rectification

12.1 Error message shown on LCD display

| | Course | Destification | | |
|---|---|--|--|--|
| Fault / error message | Cause | Rectification | | |
| System does not respond | No voltage supply. | Check the voltage supply to the door operator and the control. | | |
| Door travels to the CLOSED end position when the OPEN button is pressed Door travels to the OPEN end position when the CLOSE button is pressed | Rotating field is connected wrongly. | Check the rotating field and set direction to clockwise, if necessary. | | |
| FAULT – X | internal software or hardware fault. | RESET using the circuit board buttons: \rightarrow "8.5 RESETTING the control without an LCD monitor" | | |
| SAFETY CIRC. | The safety circuit is interrupted. X3 / 1+2 Control safety circuit EMERGENCY STOP, slack rope switch X6 / 1+2 ON / OFF internal X11 / 4+8 Safety circuit of door operator AWG X14 / 8+4 Interface RS485 X2 / B1+B2 Safety circuit of door operator MEC X3 / 3+4 External stop button X7 / 1+2 Internal stop button | Check safety circuit, localise interruption and rectify problem. | | |
| ERROR RUNTIME | The programmed running time has been exceeded. | Check the path of the door/gate and the running time. Re-programme the running time, if necessary. | | |
| ERROR AWG | Communication between absolute value encoder and control is interrupted and/or has broken down. | Check the cable and socket connections and replace, if necessary. | | |
| TERM SWITCH FAIL | The door has travelled beyond the programmed end position area. The end positions have not yet been programmed. | Move the door/gate back into the programmed area using the emergency operation facility. First, programme the end positions. | | |
| ERROR REVOLUTION | The power monitoring has been triggered | Check the door for any mechanical impairment or damage. | | |
| ERROR DIRECTION | The rotating field present is not a clockwise rotating field. | Check the rotating field and change the direction, if necessary. → "7.1 Checking the direction of rotation/direction of travel" | | |
| ERROR SKS CLS. | Closing edge safety device 1 is faulty in the CLOSING direction -> (X4 / 5-8). | Check the closing edge safety device and the spiral cable. | | |
| ERROR SKS OPEN 2 | Closing edge safety device 2 is faulty in the OPEN direction -> (X4 / 11+12) input 2 | Check the closing edge safety device and the spiral cable. | | |
| ERROR STOP 2 | Safety circuit 2 is interrupted. Wicket door switch 8.2 kΩ -> (X4 / 11+12) input 2 | Check wicket door switch. | | |
| ERROR SKS CLS. 3 | Closing edge safety device 3 is faulty in the CLOSING direction -> (X20) Plug-in RADIO transmission system channel 1 | Check closing edge safety device. Check the RADIO transmission system. | | |
| ERROR SKS OPEN 3 | Closing edge safety device 3 is faulty in the Open direction> (X20) Plug-in RADIO transmission system channel 1 | Check closing edge safety device. Check the RADIO transmission system. | | |



Error messages and rectification

| Fault / error message | Cause | Rectification | | |
|-----------------------|---|---|--|--|
| ERROR STOP 3 | Safety circuit 3 is interrupted. -> (X20) Plug-in RADIO transmission system channel 1 | Check the safety circuit. Check the RADIO transmission system. | | |
| ERROR SKS CLS. 4 | Closing edge safety device 4 is faulty in the CLOSING direction -> (X20) Plug-in RADIO transmission system channel 2 | Check closing edge safety device. Check the RADIO transmission system. | | |
| ERROR SKS OPEN 4 | Closing edge safety device 4 is faulty in the OPEN direction -> (X20) Plug-in RADIO transmission system channel 2 | Check closing edge safety device. Check the RADIO transmission system. | | |
| ERROR STOP 4 | Safety circuit 4 is interrupted. -> (X20) Plug-in RADIO transmission system channel 2 | Check the safety circuit. Check the RADIO transmission system. | | |
| ERROR SKS-TEST | Testing of attached airwave bar was unsuccessful. | Check the DW pressure switch, spiral cable and rubber profile. Check the DW-POINT setting. | | |
| | Test of radio transmission systems 1 – 4 failed. | CHECK THE RADIO TRANSMISSION SYSTEM. Check whether the right relay MOD was selected for the transmission system. → "G. Functions for external accessories" on page 39 | | |
| ERROR LIGHT BAR | The installed photocell indicates a permanent fault. > (X4 / 1-4) | Check photocell (function and alignment). Check cabling. | | |
| ERROR LIGHT BAR 2 | The installed photocell indicates a permanent fault. -> (X4 / 9+10) input 1 | Check photocell (function and alignment). Check cabling. | | |
| ERROR LB TEST | Test of two-wire photocell failed. | Check photocell (function and alignment). Check cabling. | | |
| ERROR STOP-TEST | Test of wicket door switch (8.2 kΩ) failed. –> Input 2 | Check wicket door switch. | | |
| ERROR TRAPIN | Draw-in protection test (additional module) failed. –> Relay MOD21 | Check photocell (function and alignment). Check cabling. | | |
| ERROR CYLINDER | The monitoring limit switch for the lock system for threshold-less wicket doors has failed to trigger within 10 seconds of an OPEN command being given. | Check limit switch of cylinder. | | |
| ERROR MSBUS | Communication between the control and the MS BUS module attached is interrupted. | Check the cable and socket connections and replace, if necessary. | | |
| ERROR INVERTER | Communication fault. Communication between frequency converter and control CS310 interrupted and/or broken down. Bridge (F) missing between DIC and 0V. | Check communication cable (C) and plug-in connections to control and frequency converter. Use bridge (F) between DIC and 0V (only with frequency converter type V20). Confirm with the STOP button. | | |



| Fault / error message Cause | | Rectification | | |
|-----------------------------|---|---|--|--|
| ERROR INVERTER 1 | Overcurrent. – Motor rating does not correspond to converter rating. – Short-circuit in the motor cable. – Earth leakage. | Check motor rating / inverter rating. Check motor / motor cable for short-circuit and earth leakage. Adjust the motor parameter settings to the information on the type plate. Check that the the door/gate system runs smoothly. Check the spring balance in sectional doors. Confirm with the STOP button. | | |
| ERROR INVERTER 2 | Overvoltage. Mains voltage too high. Motor is working generator-based due to ramping down too fast or due to an active load which is driving the motor. | Check the voltage supply to the door operator and the control. Confirm with the STOP button. | | |
| ERROR INVERTER 3 | Undervoltage. — Mains voltage too low. — Mains voltage supply failed. | Check the voltage supply to the door operator and the control. Check that all connections are firmly attached. Confirm with the STOP button. | | |
| ERROR INVERTER 4 | Inverter overtemperature. – Inverter overloaded. – Ambient temperature too high. | Check motor rating / inverter rating. Adjust the motor parameter settings to the information on the type plate. Check duty cycle. Check that the the door/gate system runs smoothly. Check the spring balance in sectional doors. Confirm with the STOP button. | | |
| ERROR INVERTER 5 | Inverter I2T – Inverter overloaded. – Motor rating does not correspond to converter rating. – Load cycle too high. | Check motor rating / inverter rating. Adjust the motor parameter settings to the information on the type plate. Check load cycle. | | |
| ERROR INVERTER 11 | Motor overtemperature 12.T – Motor overloaded. | Check that the the door/gate system runs smoothly. Check the spring balance in sectional doors. Confirm with the STOP button. | | |
| ERROR INVERTER 51 | Internal fault. | - Get in touch with our customer service. | | |
| ERROR INVERTER 52 | Internal fault. | - Get in touch with our customer service. | | |
| ERROR INVERTER 60 | Internal fault. | - Get in touch with our customer service. | | |
| ERROR INVERTER 72 | Internal fault. | Get in touch with our customer service. | | |
| ERROR INVERTER 85 | External fault. — External fault through command input using terminals. | Check connection terminals of communication cable (D) on inverter. Confirm with the STOP button. | | |

If other faults or error messages occur, please contact our customer service.

After rectifying the cause of the error, the power supply to the control must be turned off once and/or the control must be restarted (> INPUT menu > parameter RESTART > ON) in the event of the following errors:

- ERROR DIRECTION
- ERROR RUNTIME
- TERM SWITCH FAIL



Error messages and rectification

12.2 Error message via LED indicator

LED H4 (green, main circuit board)

| Fault / error message | LED indicator | Remarks |
|-----------------------|---------------|--------------------------|
| No operating voltage | Off | No power supply present. |

LED H6 (red, main circuit board)

| | 1 | |
|-----------------------|--|--|
| Fault / error message | LED indicator | Remarks |
| SAFETY CIRC. | Flashes 1 x | Safety circuit is interrupted. — Check safety circuit, localise interruption and rectify problem. |
| ERROR AWG | Flashes 2 x | Signal transmission between absolute value encoder and control interrupted and/or broken down. Check the cable and socket connections and replace, if necessary. |
| TERM SWITCH FAIL | Flashes 3 x | The door has travelled beyond the programmed end position area or the end positions have not yet been programmed. First, programme the end positions. Move the door/gate back into the programmed area using the emergency operation facility. |
| ERROR DIRECTION | Flashes 4 x | The rotating field present is not a clockwise rotating field. − Check the rotating field and change the direction, if necessary. → "7.1 Checking the direction of rotation/direction of travel" |
| ERROR REVOLUTION | Flashes 5 x | The power monitoring has been triggered. – Check the door for any mechanical impairment or damage. |
| ERROR RUNTIME | Flashes 6 x | The programmed running time has been exceeded. — Check the path of the door and the running time. — Re-programme the running time, if necessary. |
| ERROR INVERTER | Flashes 7 x | Communication between frequency converter and control CS310 interrupted and/or broken down. – Check data cable (D) and socket connections. – Confirm with the STOP button. |
| ERROR MSBUS | Flashes 9 x | Communication error between the control and the installed MS BUS end device. — Check the cable and socket connections and replace, if necessary. |
| ERROR SKS | Continuous light Travel only possible in deadman mode | Closing edge safety device faulty in OPENING or CLOSING direction. Check the closing edge safety device and the spiral cable and, if necessary, check the RADIO transmission system. |
| ERROR LIGHT BAR | Continuous light Travel in CLOSING direction only possible in deadman mode | The installed photocell indicates a permanent fault. – Check photocell (function and alignment). – Check cabling. |



13. Technical data

13.1 Mechanical and electrical data

| Housing dimensions (W x H x D): | 215 x 275 x 190 mm (FU-I 0.75 kW) 245 x 455 x 190 mm (FU-E 0.75 kW, FU-E 1.5 kW / 230V / 1~) 260 x 550 x 245 mm (FU-E 1.5 kW / 400V / 3~ FU-E 3.0 kW / 400V / 3~ FU-E 4.0 kW / 400V / 3~) | | | |
|---|--|--|--|--|
| Installation: | Fix vertically to the wall at a minimum height of 1,100 mm | | | |
| Power supply via | | | | |
| L1, N, PE: | 230V/1~ , 50/60Hz (0.75 kW / 1.5 kW) | | | |
| L1, L2, L3, N, PE: | 400V/3~ , 50/60Hz (1.5 kW / 3.0 kW / 4.0 kW) | | | |
| Maximum rated motor current: | 230V/1~/0.75 kW -> 3.9 A 230V/1~/1.5 kW -> 7.8 A 400V/3~/1.5 kW -> 4.1 A 400V/3~/3.0 kW -> 7.3 A 400V/3~/4.0 kW -> 8.8 A | | | |
| Fuse protection: | 230V/1~/0.75 kW -> 16 A 230V/1~/1.5 kW -> 20 A 400V/3~/1.5 kW -> 16 A 400V/3~/3.0 kW -> 16 A 400V/3~/4.0 kW -> 16 A | | | |
| | Fuse elements with K-type characteristic. | | | |
| | If supplied with three-phase current, only blocks of three automatic circuit-breakers must be used. | | | |
| Internal consumption of the control: | max. 750 mA | | | |
| Control voltage: | 24 V DC, max. 500 mA; protected by self-resetting fuse for external sensor systems. | | | |
| Control inputs: | 24 V dcall inputs must be connected so that they are potential-free. Minimum signal duration for input control command > 100 ms | | | |
| Control outputs: | 24 V dc, max. 500 mA | | | |
| RS485 A and B: | Only for electronic limit switches RS485 level, terminated with 120 Ω | | | |
| Safety circuit / Emergency stop: | All input connections MUST be potential-free; if the safety circuit is interrupted, no further electrically powered movement of the operator is possible, not even in deadman mode | | | |
| Closing edge safety device input (performance level C): | Performance level C for electrical closing edge safety devices with 8.2 k Ω terminating resistor and for dynamic optical systems | | | |

| Photocell (performance level D): | If the photocell is used as a D performance level protection system, it must be checked at regular intervals – at least every 6 months – to ensure that the system is working properly. MFZ two-wire photocells are self-testing; this requirement can be dispensed with in this case. |
|-------------------------------------|---|
| Display (LCD): | Only an original MFZ LCD monitor may be used. |
| Relay outputs: | If inductive loads are switched (e.g. further relays or brakes), these must be equipped with suitable interference suppression (such as recovery diode, varistors or RC circuits). Potential-free normally open contact; min. 10 mA; max. 230 V Ac / 4A. Once contacts have been used for power circuits, they can no longer be used for extra-low current circuits. |
| Temperature range: | Operation: -10°C +45°C Storage: -25°C +70°C |
| Air humidity: | Up to 80% with no condensation |
| Vibrations: | Low-vibration mounting, e.g. on a masonry wall |
| Protection grade: | IP 54 |
| Weight: | approx. 1.8 kg (Version FU-I 0.75 kW) approx. 4.5 kg (Version FU-E 0.75 kW) approx. 5,5 kg (Version FU-E 1.5 kW / 3.0 KW / 4.0 kW) |



Technical data

13.2 Functional safety category and performance level according to EN ISO 13849-1

| Implementation | MTTF _D Electronics | MTTF _D Complete, with output contactor (1) | DC _{avg} | Category | Performance level |
|--|--|--|--|--|--|
| Input terminal X3, X6, X7, X11 Interrupts voltage supply to the output relays and main contactor, independently of the CPU. Signal received by CPU. | 1175 years | 191 years | 85.3% | 3 | GB |
| Input terminal X3, X7 Interrupts the power supply to the main contactor. Signal to CPU. | 1175 years | 191 years | - | В | В |
| Input terminal X11 For determining the position, and for end position detection. Safety through checking plausibility of drive commands with signals received. | 1062 years | 188 years | 85.6% | 2 | GB |
| Input terminal X15 Safeguarded through excess travel stop. Inputs are evaluated by the CPU. | 1248 years | 193 years | 85.5% | 2 | GB |
| Input terminal X4 Impulse evaluation through CPU. Faults are detected through plausibility check in the CPU. The frequency must lie between 130 and 190 Hz. The function is tested by switching on the supply voltage (T117, IC111) of the photocell before every run and every two minutes in standby. If activated in the CLOSING direction, the door stops or reverses. | 1000 years | 186 years | 85.7% | 2 | GB |
| | Input terminal X3, X6, X7, X11 Interrupts voltage supply to the output relays and main contactor, independently of the CPU. Signal received by CPU. Input terminal X3, X7 Interrupts the power supply to the main contactor. Signal to CPU. Input terminal X11 For determining the position, and for end position detection. Safety through checking plausibility of drive commands with signals received. Input terminal X15 Safeguarded through excess travel stop. Inputs are evaluated by the CPU. Input terminal X4 Imputs evaluation through CPU. Faults are detected through plausibility command and 190 Hz. The function is tested by switching on the supply voltage (T117, IC111) of the photocell before every run and every two minutes in standby. If activated in the CLOSING | ImpermentationElectronicsInput terminal X3, X6, X7, X11 Interrupts voltage supply to the output relays and main contactor, independently of the CPU. Signal received by CPU.1175 yearsInput terminal X3, X7 Interrupts the power supply to the main contactor. Signal to CPU.1175 yearsInput terminal X11 For determining the position, and for end position detection. Safety through checking plausibility of drive commands with signals received.1062 yearsInput terminal X15 Safeguarded through excess travel stop. Inputs are evaluated by the CPU.1248 yearsInput terminal X4 Impulse evaluation through CPU. Faults are detected through plausibility check in the CPU. The frequency must lie between 130 and 190 Hz. The function is tested by switching on the supply voltage (T117, IC111) of the photocell before every run and every two minutes in standby. If activated in the CLOSING1000 years | ImplementationMTTFp ElectronicsComplete, with output contactor (1)Input terminal X3, X6, X7, X11 Interrupts voltage supply to the output relays and main contactor, independently of the CPU. Signal received by CPU.1175 years191 yearsInput terminal X3, X7 Interrupts the power supply to the main contactor. Signal to CPU.1175 years191 yearsInput terminal X11 For determining the position, and for end position detection. Safety through checking plausibility of drive commands with signals received.1062 years188 yearsInput terminal X15 Safeguarded through excess travel stop. Inputs are evaluated by the CPU.1000 years186 yearsInput terminal X4 Impulse evaluation through CPU. | ImplementationMTTF_b ElectronicsComplete, with output contactor (1)DC_avgInput terminal X3, X6, X7, X11 Interrupts voltage supply to the output relays and main contactor, independently of the CPU.1175 years191 years85.3%Input terminal X3, X7 Interrupts the power supply to the main contactor. Signal to CPU.1175 years191 years-Input terminal X11 For determining the position, and for end position detection. Safety through checking plausibility of drive commands with signals received.1062 years188 years85.6%Input terminal X15 Safeguarded through excess travel stop. Inputs are evaluated by the CPU.1000 years186 years85.7%Input terminal X4 Impulse evaluation through CPU. Faults are detected through plausibility check in the CPU. The frequency must lie between 130 and 190 Hz. The function is tested by switching on the supply voltage (T117, IC111) of the photocell before every run and every two minutes in standby. If activated in the CLOSING1000 years | ImplementationMTTF_b ElectronicsComplete, with output contactor (1)DC_{avg}CategoryInput terminal X3, X6, X7, X11 Interrupts voltage supply to the output relays and main contactor, independently of the CPU.1175 years191 years85.3%3Input terminal X3, X7 Interrupts the power supply to the main contactor.1175 years191 years-BInput terminal X11 For determining the position, and for end position detection. Safety through checking plausibility of drive commands with signals received.1062 years188 years85.5%2Input terminal X15 Safeguarded through excess travel stop. Inputs are evaluated by the CPU.1000 years186 years85.7%2Input terminal X4 Impulse evaluated through CPU. Faults are detected through plausibility check in the CPU. The frequency must lie between 130 and 190 Hz. The function is tested by switching on the supply voltage (1117, IC111) of the photocell before every run and every two minutes in standby. If activated in the CLOSING1000 years186 years85.7%2 |

DCAverage diagnostic coverageMTTFMean time to dangerous failure



14. Maintenance

The CS 310 FU control is maintenance-free.

🛕 DANGER!

Life-threatening danger due to electric shock!

The control unit or door system MUST be disconnected from the electricity supply before carrying out any electrical work! Take measures to ensure that the power supply remains disconnected for the duration of the work.

The following points must be taken into account when carrying out maintenance on the door system:

- Maintenance must only be carried out by authorised persons.
- Directive ASR A1.7 must be complied with.
- Worn or faulty parts must be replaced.
- Only approved parts may be installed.
- All maintenance work must be documented.
- Replaced faulty parts must be disposed of properly in accordance with the materials they contain and local regulations.





15. EC Declaration of Conformity

We hereby declare that the product described below: **CS 310 FU Door Control** is in conformity with all essential requirements of the

Machinery Directive 2006/42/EC.

In addition, the logic unit is in conformity with all the provisions of the

- EC Construction Products Regulation (305/2011/EC)
- Electromagnetic Compatibility Directive (2014/30/EC)
- Low Voltage Directive (2014/35/EC).

The following standards were applied:

EN 60204-1: 2006 Safety of machinery, electrical equipment of machines; Part 1: General requirements

EN ISO 12100: 2010 Safety of machinery – general principles for design risk assessment and risk reduction

DIN EN 12453: 2000 Safety in use of power operated doors - Requirements

prEN 12453: 2014 Safety in use of power operated doors (exclusively for items 1.3.7 and 1.4.3 of Annex I of the Machinery Directive)

DIN EN 61000-6-2 Electromagnetic compatibility (EMC) -Part 6-2: Generic standards - Immunity for industrial environments

DIN EN 61000-6-3 Electromagnetic compatibility (EMC) - Part 6-3: Generic standards - Emission - standard for residential, commercial and light-industrial environments

DIN EN 60335-1: 2012 Household and similar electrical appliances - Safety -Part 1: General requirements

DIN EN 60335-2-103: 2003 Household and similar electrical appliances - Safety - Part 2-103: Particular requirements for drives for gates, doors and windows The relevant technical documentation is compiled in accordance with Annex VII (B) of the EC Machinery Directive 2006/42/EC We undertake to transmit, in response to a reasoned request by the market surveillance authorities, this information in electronic form within a reasonable term.

EC type examination certificate No. 4420513133301 TÜV NORD CERT GmbH (NB 0044) Langemarckstrasse 20 D - 45141 Essen, Germany

Person authorised to compile the relevant technical documentation: MFZ Antriebe GmbH & Co. KG, Neue Mühle 4 D-48739 Legden, Germany

The logic unit must not be put into service until the machinery into which the logic unit is to be incorporated has been declared in conformity with the provisions of the Machinery Directive 2006/42/EC.

Place / Date: Legden, 20/04/2016

Manufacturer's signature

ppa. Wenn

Dirk Wesseling

Position of signatory Management

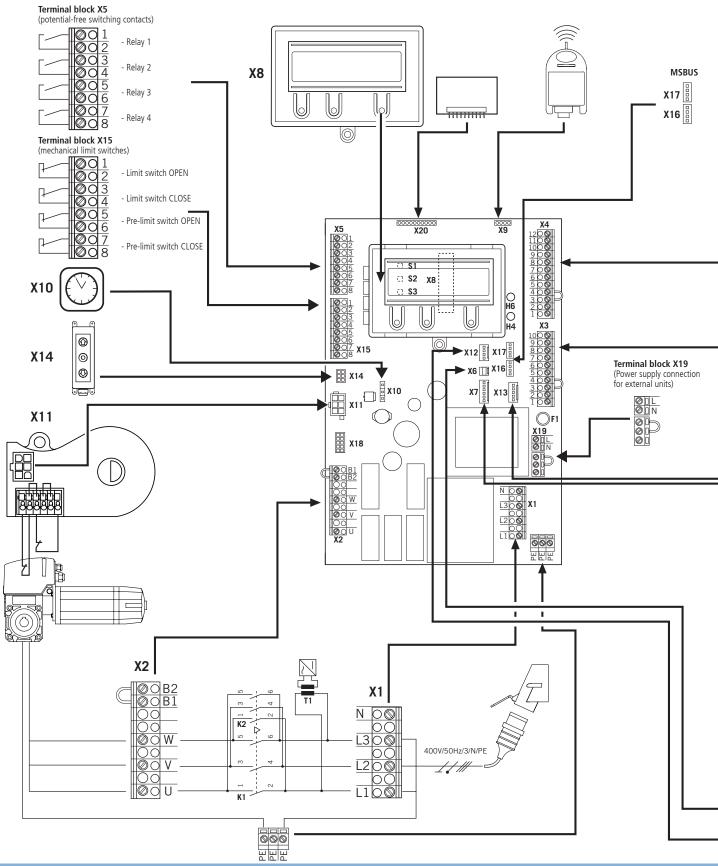




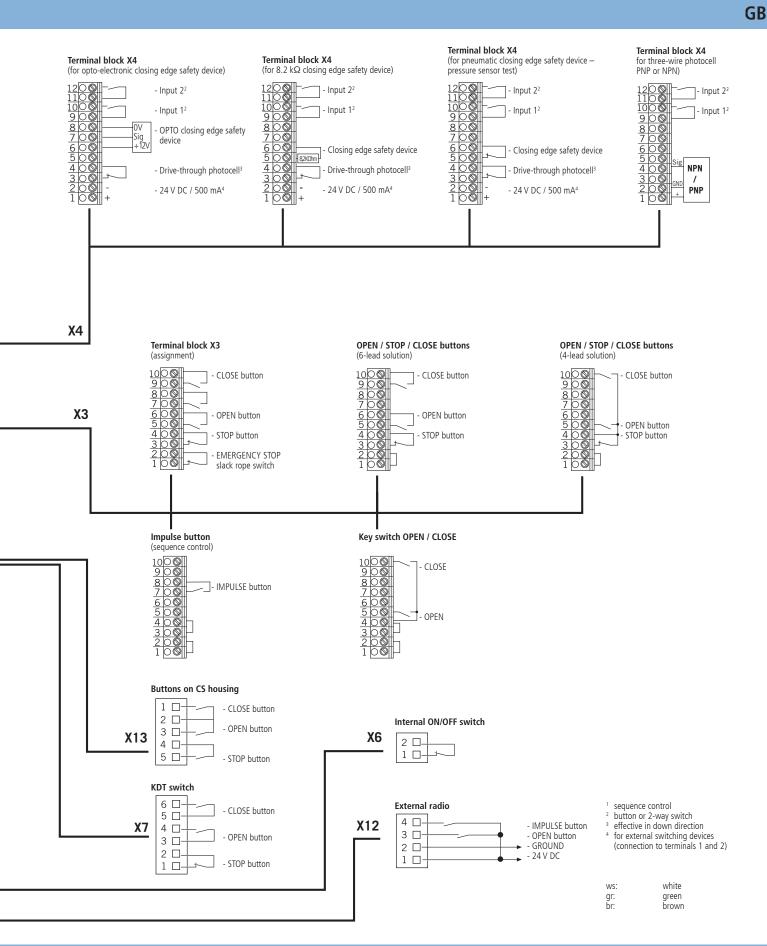


16. Appendix

16.1 Overview of connections



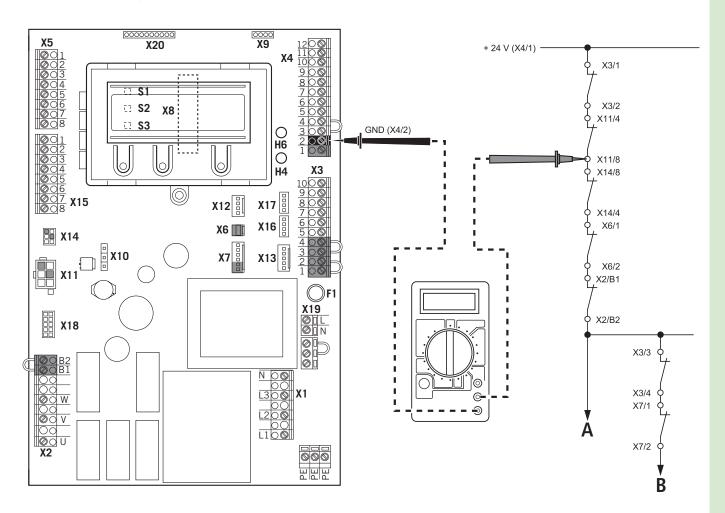






Appendix

16.2 Measuring points, safety circuit



NOTICE:

The measurement range must be set for 24 V-DC.

- A Emergency Stop
- B Stop
- Measure at all measuring points on the diagram in order to locate the interruption.













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